



## OPERATING INSTRUCTIONS TIG inert gas welding equipment

**TIGER DIGITAL 230 DC / AC/DC ULTRA/HIGH  
TIGER DIGITAL 180 DC / AC/DC ULTRA/HIGH  
TIG.STAR 170 DC / AC/DC**

**REHM SCHWEISSTECHNIK**



## Operating instructions

TIG inert gas welding equipment

**TIGER DIGITAL 230 AC/DC    ULTRA**  
**TIGER DIGITAL 230 AC/DC    ULTRA**  
**TIGER DIGITAL 180 AC/DC    ULTRA**  
**TIGER DIGITAL 180 AC/DC    ULTRA**

**TIGER DIGITAL 230 AC/DC    HIGH**  
**TIGER DIGITAL 230 DC        HIGH**  
**TIGER DIGITAL 180 AC/DC    HIGH**  
**TIGER DIGITAL 180 DC        HIGH**

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## List of contents

	<b>Product identification</b>	<b>2</b>
<b>1</b>	<b>Introduction</b>	<b>6</b>
1.1	Foreword	6
1.2	General description	7
1.2.1	Principle of the TIG inert gas welding process	8
1.2.2	Scope of application of TIG welding equipment	8
1.2.3	Intended use	8
1.3	Symbols used	9
<b>2</b>	<b>Safety information</b>	<b>10</b>
2.1	Warning symbols in these operating instructions	10
2.2	Warning symbols on the system	10
2.3	Notes and requirements	11
<b>3</b>	<b>Unit description</b>	<b>13</b>
<b>4</b>	<b>Function description</b>	<b>15</b>
4.1	Overview of the operating panel	15
4.2	Operation description	16
4.2.1	Controls	16
4.2.2	Operating functions	17
4.3	Switch on	21
4.4	Peculiarities of the operating panel	21
<b>5</b>	<b>Corner menu functions</b>	<b>22</b>
5.1	Corner menu welding processes (top left)	22
5.1.1	Electrode welding	22
5.1.2	Electrode BOOSTER function	22
5.2	Corner menu operating mode (top right)	23
5.2.1	2 cycle operating mode	23
5.2.2	4 cycle operating mode	24
5.2.3	TIG spot welding	24
5.2.4	TIG interval	25
5.3	High-frequency (HF) ignition	26
5.3.1	Welding with HF ignition	26
5.3.2	Welding without HF ignition	27
5.4	Corner menu welding process (bottom right)	28
5.4.1	Time pulses	28
5.4.2	Hyper pulses	28
5.5	Corner menu polarity (bottom left)	29
5.5.1	Alternating current (~)	29
5.5.2	Dual Wave (=/~)	29
5.5.3	DC positive positive pole (+)	29
5.5.4	DC negative pole (-)	30
<b>6</b>	<b>Parameter settings</b>	<b>31</b>
6.1	Setting the TIG welding parameters	31
6.1.1	Gas pre-flow time	31
6.1.2	Ignition power	31
6.1.3	Starting current	32
6.1.4	Slope-up time	32
6.1.5	Welding current $I_1$ and pulse time $t_1$	32
6.1.6	Welding current $I_2$ and pulse time $t_2$	32
6.1.7	Automatic pulsing	33
6.1.8	Manual pulsing	34
6.1.9	Slope-down time	34
6.1.10	End crater current $I_e$	34
6.1.11	Gas post flow time	35

6.2	AC settings menu	36
6.2.1	AC waveform	36
6.2.2	AC frequency (Hz)	36
6.2.3	AC balance (■)	36
6.2.4	Further settings for DualWave	36
6.3	Menu spot welding and interval	37
6.3.1	Spot time	37
6.3.2	Pause time	37
6.4	Electrode welding parameters	37
6.4.1	Setting options (from left to right)	38
6.4.2	Hot Start	38
6.4.3	Welding current I1	38
6.4.4	ArcForce	38
6.4.5	Anti-stick-automatic	39
<b>7</b>	<b>Submenus</b>	<b>40</b>
7.1	Language menu	40
7.2	Assist	40
7.3	Save and load programs	42
7.3.1	Quick program buttons P1 ... P4	42
7.3.2	Memory programs 5 to 99	42
7.3.3	Manage parameter lists (folders)	43
7.4	Optional water cooling unit	45
<b>8</b>	<b>Setup / special parameters</b>	<b>46</b>
<b>9</b>	<b>Error memory</b>	<b>50</b>
<b>10</b>	<b>Indicating symbol</b>	<b>50</b>
<b>11</b>	<b>Accessories</b>	<b>51</b>
11.1	Foot-actuated remote controller TIGER DIGITAL 180/230	51
11.2	REHM TIG torch	51
11.3	Optional water cooling unit	51
<b>12</b>	<b>Commissioning</b>	<b>52</b>
12.1	Safety information	52
12.2	Working under increased electrical hazard (IEC 874, EN 60974-1, TRBS 2131 and BGR 500 KAP. 2.26)	52
12.3	Placement and transportation of the welding unit.	53
12.4	Connecting the welding unit	53
12.5	Cooling the welding unit	53
12.6	Guidelines for working with welding current sources	54
12.7	Connecting the welding leads and the torch	54
12.8	Connection of external components	54
<b>13</b>	<b>Operation</b>	<b>55</b>
13.1	Safety information	55
13.2	Electrical hazard	55
13.3	Instructions for your personal safety	55
13.4	Fire protection	56
13.5	Ventilation	56
13.6	Checks before switching on	57
13.7	Connecting the grounding cable	57
13.8	Practical instructions for use	57
<b>14</b>	<b>Faults TIG welding unit</b>	<b>60</b>
14.1	Safety information	60
14.2	Table of faults	60
14.3	Error messages	63



<b>15</b>	<b>Maintenance work</b>	<b>65</b>
15.1	Safety information	65
15.2	Maintenance table	65
15.3	Cleaning the inside of the unit	66
15.4	Proper disposal	66
<b>16</b>	<b>Technical data</b>	<b>67</b>
<b>17</b>	<b>Accessories</b>	<b>71</b>
<b>18</b>	<b>Circuit diagrams</b>	<b>73</b>
<b>19</b>	<b>INDEX</b>	<b>79</b>

# **1 Introduction**

## **1.1 Foreword**

Dear Customer,

You have purchased a REHM inert gas welding system, a renowned German brand name.

We thank you for the confidence you have placed in our quality products.

Only components of the highest quality are used in TIGER DIGITAL equipment.

To enable a long service life even under the toughest conditions all REHM equipment is manufactured using only parts that comply with our strict quality demands.

The TIGER DIGITAL has been developed and designed according to the generally accepted rules for technology and safe operation. All relevant legal regulations have been observed and complied with. Conformity is declared and is marked with the CE symbol.

REHM welding systems are manufactured in Germany and therefore bear the "Made in Germany" quality label.

Since REHM strives to immediately take advantage of technical progress, it reserves the right to adapt the design of the welding equipment at any time to the latest technical requirements.

## 1.2 General description



Fig.1 TIGER DIGITAL (in the background with a water cooling unit)

### **1.2.1 Principle of the TIG inert gas welding process**

In TIG welding the arc burns freely between a tungsten electrode and the workpiece. The inert gas is a noble gas such as argon, helium or a mixture of these.

One pole of the power source is connected to the tungsten electrode, the other to the workpiece. The electrode is the current conductor and arc carrier (continuous electrode). The filler material is introduced in the form of a rod or wire by hand or a separate cold wire feed unit. The tungsten electrode, the weld pool and the molten end of the filler material are protected against the ingress of atmospheric oxygen by inert shielding gas that escapes from the protective gas nozzle arranged concentrically around the electrode.

### **1.2.2 Scope of application of TIG welding equipment**

TIGER DIGITAL DC welding machines are DC sources. They are suitable for welding all carbon and alloy steels, stainless steels and non-ferrous metals.

TIGER DIGITAL AC/DC welding machines are AC and DC sources. They can be used for processing all carbon and alloy steels, stainless steels, non-ferrous metals, aluminium and aluminium alloys.

### **1.2.3 Intended use**

TIGER DIGITAL welding machines may be used only for TIG or electrode welding as intended.

REHM welding devices are designed for welding various different metallic materials such as unalloyed and alloyed steels, stainless steels, copper, titanium and aluminium.

Please also observe the special rules that apply to your applications.

REHM welding machines are designed for use in hand-held and machine-guided operation.

REHM welding machines are, except when this is expressly stated in writing by REHM, only for sale to commercial / industrial users and are only intended to be used by commercial / industrial users. The machines may only be operated by persons who trained in the use and maintenance of welding equipment.

Welding power sources may not be installed in areas with increased electrical risk.

This manual contains rules and guidelines for the intended use of your system. Only compliance with these guidelines shall be considered as proper use. Risks and damages incurred due to any other use is the responsibility of the operator. Use under special requirements may necessitate the observance of particular regulations.

If in doubt, ask your competent safety officer or contact the REHM customer service department.

The special instructions listed in the supplier documentation for intended use must be observed.

National regulations also apply without restriction to the operation of the system.

Welding power sources may not be used to defrost pipes.

Intended use also includes compliance with the prescribed assembly, disassembly and reassembly, commissioning, use, maintenance and disposal measures. Please make particular note of the information in Section 2 Safety information and Section 15.4 Proper disposal.

The system may only be operated under the aforementioned conditions. Any other use is considered unintended use. The consequences of unintended use rests with the operator.

## 1.3 Symbols used

### Typographic distinctions

- Enumerations proceeded by a bullet point: General enumerations
- Enumerations proceeded by a square: Work or maintenance steps that must be performed in the order listed.

### ➔ Section 2.2, Warning symbols on the system

Cross-reference: Here to Section 2.2 Warning symbols on the **system**, warning symbols on the system

**Bold text** is used for emphasis

### Note!

... indicates practical tips and other particularly useful information.



### Safety symbols

The safety symbols used in this manual: ➔ **Section 2.1**

## 2 Safety information

### 2.1 Warning symbols in these operating instructions

#### Warnings and symbols



This or a symbol that more accurately specifies the risk can be found in all of the safety instructions given in these operating instructions where there is danger to life and limb.

One of the signal words below (Danger!, Warning!, Caution!) is used to indicate the severity of the risk:

**Danger!** ...warning of immediate danger.

Death or serious injury may result if the warning is not heeded.

**Warning!** ... of a potentially dangerous situation.

Death or serious injury may result if the warning is not heeded.

**Caution!** ... warns of a potentially harmful situation.

Slight or minor injuries or property damage may result if the warning is not heeded.

**Important!**



Notice of a potentially harmful situation. The product or an object in the vicinity may be damaged if the warning is not heeded.



Materials that are hazardous to health or the environment. Materials/operating materials that must be handled or disposed of in a legally conformant way.

### 2.2 Warning symbols on the system

Identify hazards and hazards on the system.



**Danger!**

**Risk of electrical shock!**

Non-observance may result in death or injury.

## 2.3 Notes and requirements

### Hazards of non-compliance

The system was developed and designed by the generally accepted rules of technology.

Nevertheless, residual dangers to the life and limb of the operator or the risk of damage to the system or other property may still arise in the use of the system.

Safety equipment must never be dismantled or put out of operation as this will result in dangerous hazards and the intended use of the system is no longer guaranteed. The dismantling of safety devices for equipping, repairing and maintenance is described in detail. The safety devices must be refitted immediately on completion of such work.



When using external aids and agents (for example, solvents for cleaning) the user of the system is responsible for ensuring the safety of the unit.

All safety instructions and warnings and the nameplate on / near the system must be kept visible and legible.

### Safety instruction

The occupational safety and health regulations serve as safety references. They must be observed.

The special safety instructions given in the main text must also be observed in addition to the safety instructions given in this section.

Beside the advice given in these operating instructions, the general safety and accident prevention regulations (in Germany, among others UVV BGV A3, TRBS 2131 and BGR 500 Chapter 2:26 (previously VGB 15) "Welding, cutting and allied processes" and particularly the conditions for arc welding and cutting contained therein or the corresponding national regulations) must be observed.

Also observe the safety information signs on the factory floor of the operator.



### Applications

REHM welding machines are, except when this is expressly stated in writing by REHM, only for sale to commercial / industrial users and are only intended to be used by commercial / industrial users.

TIGER DIGITAL TIG inert gas welding systems may only be used

- as intended
- in an absolutely perfect condition



TIGER DIGITAL inert gas welding equipment is designed in accordance with EN 60974-1 Arc welding equipment - welding power sources for overvoltage category III and pollution degree 3 and in accordance with EN 60974-10 Arc welding equipment - electromagnetic compatibility (EMC) for Group 2 Class A and should be suitable for use in all areas, except residential areas that are connected directly to a public low-voltage supply system. It may possibly be difficult to ensure electromagnetic compatibility in these areas due to both conducted and radiated interference. For this purpose the use of appropriate measures to meet the requirements (filters for mains connection, shields such as shielded cables, the shortest possible welding cables, earthing of the workpiece, potential equalization) and assessment of the environment (such as computers, controllers, radio and television broadcasters, adjacent people, for example required in the use of cardiac pacemakers) are required. The responsibility for any fault lies with the user. For more information and recommendations, see, inter alia, DIN EN60974-10: 2008-09, Annex A.

**Environmental conditions**

Operation and storage of the unit outside the specified range is considered to be improper. The manufacturer is not liable for any resulting damage.

Ambient air temperature range:

- In operation: -10°C to +40°C (14 °F to 104 °F)
- During transport and storage: -20°C to +55°C (-4 °F to 131 °F)

Relative humidity:

- to 50% at 40°C (104 °F)
- to 90% at 20°C (68 °F)

Ambient air:

Free of unusual amounts of dust, acids, corrosive gases or substances, etc., unless they are produced during welding.

Altitude above sea level: Up to 2000m (6500 ft)

**Requirements on the mains supply**

The unit may be connected and operated from a single phase 2-wire system with earthed neutral conductor.

**For TIGER DIGITAL 230 AC/DC and TIGER DIGITAL 230 DC**

The unit complies with IEC61000-3-12.

**For TIGER DIGITAL 180 AC/DC and TIGER DIGITAL 180 DC**

Caution: This unit does not meet the requirements of EN / IEC 61000-3-12.

If the unit is to be connected to a public power supply then it may be necessary, after consultation with the operator of the supply network, to ensure that the unit can be connected.

This is the responsibility of the operator or the user of the unit.

**Qualification of the operating personnel**  
**Purpose of the document**

REHM welding equipment should be operated only by persons who are trained and instructed in the use and maintenance of welding equipment. Only qualified, assigned and trained personnel may work on and with the system.

These operating instructions contain important information on how this unit can be operated safely, properly and economically. A copy of the operating instructions must be constantly at hand in a suitable place at the site of use of the system. Before using the system be sure to read the information compiled in these operating instructions. These include important instructions on use of the equipment that enable the full technical advantages of the REHM equipment to be exploited. See also the information on repair and maintenance, operating safety and functional reliability.

**Changes to the system**

These operating instructions are not a substitute for the practical teaching by the REHM service personnel.

Documentation for any additional operation that may be present must also be observed.

Changes to the system or the mounting or incorporation of additional equipment is not permitted. Doing so will invalidate any warranty and liability claims.

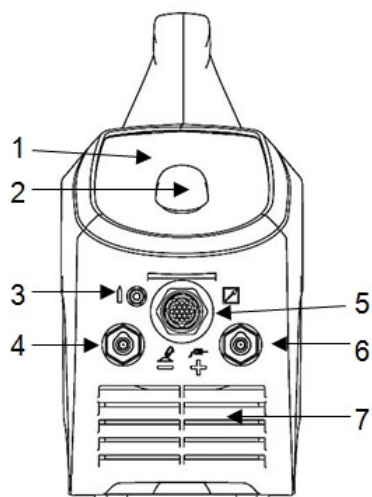
Third-party intervention and putting out of operation of safety devices invalidates all warranty claims.



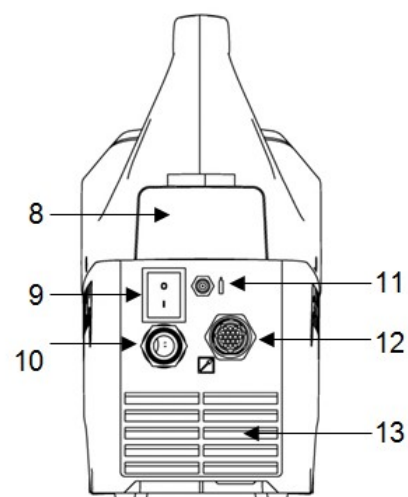
### 3 Unit description

#### TIGER DIGITAL without water cooling

Front Ansicht

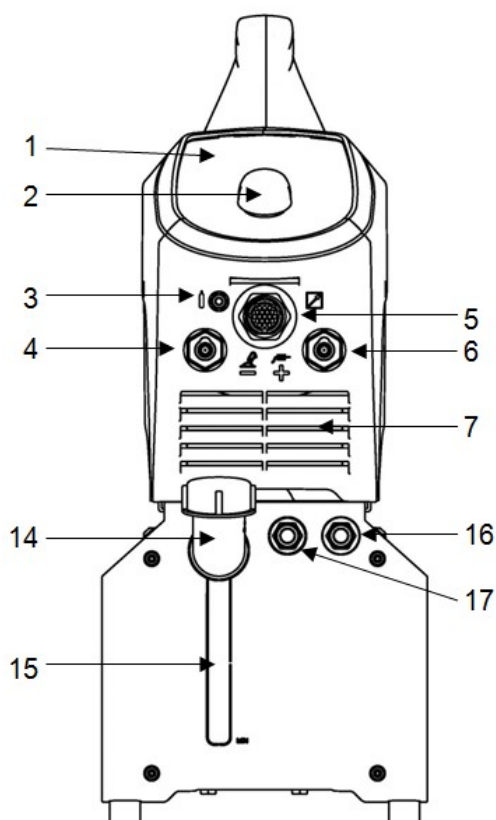


Rück Ansicht



#### TIGER DIGITAL with optional water cooling unit

Front Ansicht



Rück Ansicht

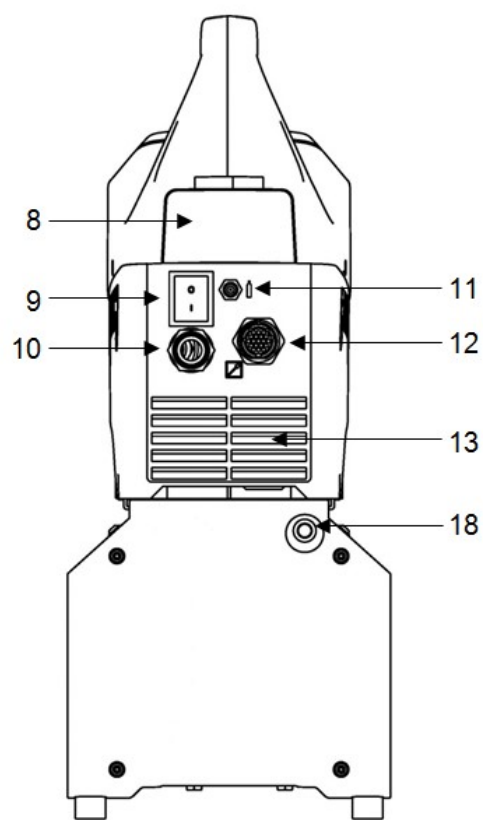









Fig.2 Unit description

No.	Symbol	Function / description
1		Control panel - See "Description of controls"
2		Control panel push and rotary encoder
3		Shielding gas connection - TIG welding torch
4		Current socket "negative" TIG: TIG welding torch Electrode: Workpiece or electrode holder
5		Torch / remote control jack
6		Current socket "positive" TIG: workpiece Electrode: Workpiece or electrode holder
7		Cooling air inlet
8		Drawer – storage for electrodes, gas nozzles, etc.
9		Main switch - On / Off
10		Power cable
11		Shield gas feed connection - shield gas cylinder
12		Water cooling unit connection – Optional
13		Cooling air outlet
14		Coolant inlet to coolant filling
15		Coolant level window
16		Connection coolant return (red)
17		Connection coolant supply (Blue)
18		Fuse water cooling unit

**Table 1 Equipment labelling on the front and back**

## 4 Function description


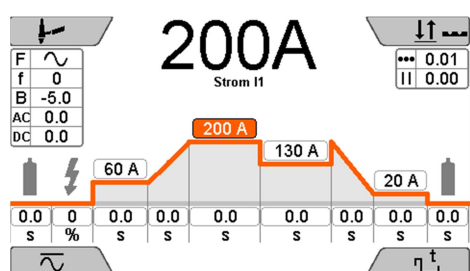

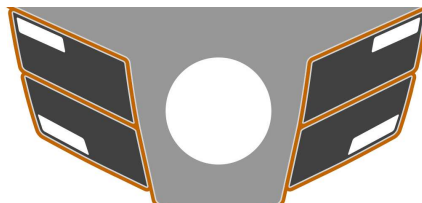
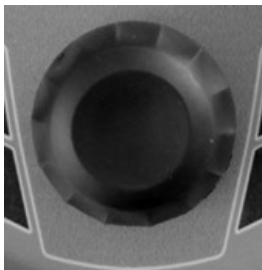
### 4.1 Overview of the operating panel



Fig.3 TIGER Digital operating panel

## 4.2 Operation description

### 4.2.1 Controls

Controls	Function									
 <p><b>Fig.4 Quick program buttons</b></p>	Quick program buttons P1-P4									
 <p><b>Fig.5 Main screen</b></p>	<p>Main screen</p> <p>Operation via rotary encoder with push-knob and buttons for menu selection in the 4 corners of the screen</p>									
 <p><b>Fig.6 Function buttons</b></p>	<p>Function buttons (from left to right)</p> <table><tr><td>Button</td><td>Submenu "Submenu"</td><td>List of all submenus</td></tr><tr><td>Button</td><td>Main screen "Home"</td><td>Jumps directly to the first screen page</td></tr><tr><td>Button</td><td>Back "Back"</td><td>Always jumps back one level</td></tr></table>	Button	Submenu "Submenu"	List of all submenus	Button	Main screen "Home"	Jumps directly to the first screen page	Button	Back "Back"	Always jumps back one level
Button	Submenu "Submenu"	List of all submenus								
Button	Main screen "Home"	Jumps directly to the first screen page								
Button	Back "Back"	Always jumps back one level								
 <p><b>Fig.7 Corner function buttons</b></p>	<p>Corner menu selection buttons</p> <p>Direct menu buttons for the selection menus located in the 4 screen corners; arranged around the rotary encoder.</p>									
 <p><b>Fig.8 Push and rotary encoder</b></p>	<p>Rotary encoder with push-knob</p> <p>Moves the pointer (cursor) on the screen clockwise or counter clockwise. Positions reached are highlighted in colour and are activated by pressing the rotary encoder knob.</p>									

## 4.2.2 Operating functions

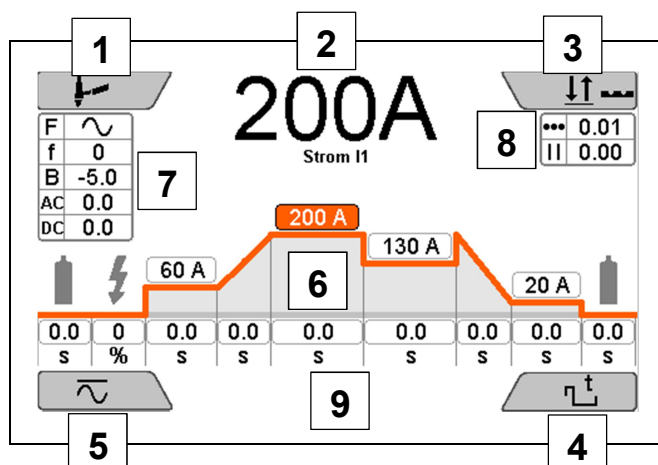



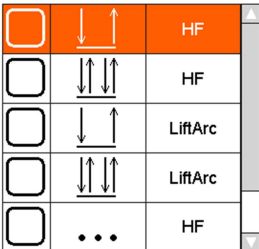




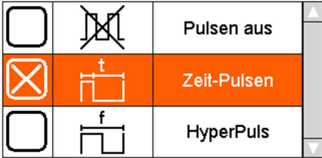


Fig.9 Screen functions

No.	Symbols	Description / function	Ultra AC/DC	Ultra DC	High AC/DC	High DC
<b>BF1</b>		<b>Corner menu welding processes</b>				
		TIG welding	✓	✓	✓	✓
		Electrode welding	✓	✓	✓	✓
		Electrode booster function	✓	✓	✓	✓
<b>BF2</b>		<b>Main display panel with function text</b>  200A Strom I1	✓	✓	✓	✓
<b>BF3</b>		<b>Corner menu operating modes</b> 				
		2 cycle: LiftArc or with HF ignition	✓	✓	✓	✓
		4 cycle: LiftArc or with HF ignition	✓	✓	✓	✓
		Spot welding with HF	✓	✓	✓	✓
		Interval with HF	✓	✓	—	—
<b>BF4</b>		<b>Corner menu pulse</b> 				

No.	Symbols	Description / function	Ultra AC/DC	Ultra DC	High AC/DC	High DC
		Pulse off	✓	✓	✓	✓
		Conventional pulsing	✓	✓	✓	✓
		High-frequency pulse (hyper pulse)	✓	✓	—	—
<b>BF5</b>		<b>Corner menu polarity</b> 				
		Alternating current (AC)	✓	—	✓	—
		Dual Wave	✓	—	—	—
		DC positive pole (DC+)	✓	—	✓	—
		DC negative pole (DC-)	✓	✓	✓	✓
<b>BF6</b>		<b>TIG welding parameter curve</b>				
		<p>The following shows the setting possibilities from left to right</p>				
		Gas pre-flow time	✓	✓	—	—
		Ignition power	✓	✓	—	—
		Starting current and starting current time	✓	✓	—	—
		Slope-up time	✓	✓	—	—
		Welding current I1 and pulse time t1 alternative t1/t2 hyperpulse frequency	✓	✓	✓	✓

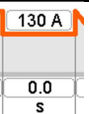

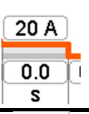

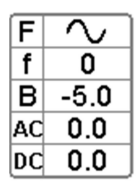
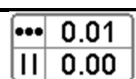














No.	Symbols	Description / function	Ultra AC/DC	Ultra DC	High AC/DC	High DC
		Welding current I2 and pulse time t2 alternative t1/t2 hyperpulse frequency	✓	✓	✓	✓
		Slope-down time	✓	✓	✓	✓
		End-crater current End-crater current time	✓ ✓	✓ ✓	✓ —	✓ —
		Gas post flow time	✓	✓	✓	✓
<b>BF7</b>		<b>Menu AC settings</b>				
		<b>F</b> AC waveform (adjustable) <b>f</b> AC frequency (adjustable) <b>B</b> AC balance (adjustable) <b>AC</b> AC time DualWave (adjustable) <b>DC</b> DC time DualWave (adjustable)	All ✓ ✓ ✓ ✓	— — — — —	Auto ✓ ✓ — —	— — — — —
<b>BF8</b>		<b>Menu spot welding and interval</b>				
		Spot time Pause time (only in interval mode)	✓ ✓	✓ ✓	— —	— —
<b>BF9</b>		<b>Status line</b>	✓	✓	✓	✓

Table 2 Operating panel main screen

No.	Symbols	Description / function	Ultra AC/DC	Ultra DC	High AC/DC	High DC
<b>BF10</b>		<b>Sub menu buttons</b>	✓	✓	✓	✓
		 Sprache / Language  Assist  Programm  Setup  Meldungen				
<b>BF11</b>	 	Back button "Home" and "Back"	✓	✓	✓	✓
<b>BF12</b>		Function Assist see Chap. 7.2	✓	✓	—	—
<b>BF13</b>		Function program (Jobs) see Chap. 7.3	✓	✓	—	—
<b>BF14</b>		Settings (Setup) see Chap. 8	✓	✓	✓	✓
<b>BF15</b>		Error message and see Chap. 9 14.3	✓	✓	✓	✓
<b>BF16</b>		Left in the status line: Operating and temperature displays	✓	✓	✓	✓
<b>BF17</b>		Right in the status line: Remote control display	✓	✓	✓	✓

**Table 3 Other control functions and submenus**



### 4.3 Switch on

The TIGER DIGITAL welding system is started with the mains switch. The screen shows the Rehm logo and the unit type for approximately 10 seconds. The display then switches to the main screen [Fig.5 Main screen]. The last active welding parameters are set. The unit is then ready for operation.

### 4.4 Peculiarities of the operating panel



The processor control provides active support to facilitate faster and easier operation:

All set parameters are saved when the unit is switched off. When the unit is switched back on the stored parameters are automatically activated. An arc must be struck for any changes to the parameters to be saved when the unit is switched off.

The currently set parameters and settings are always displayed.

If the rotary encoder [Fig.8] or button is not actuated for 20 seconds, then the unit returns automatically to welding current I1. The basic state therefore always displays the most important values; current I1 and the same starting position when operating.

## 5 Corner menu functions

### 5.1 Corner menu welding processes (top left)

The corner menu [\[BF1\]](#) is used to select the welding processes

- TIG welding
- Electrode welding
- Electrode welding BOOSTER.

Turning and pressing the rotary encoder **[Fig.8]** selects and confirms the process. Pressing the button **[Fig.6]** "Back" or "Rehm" returns to the main screen **[Fig.5]**.

The setting of the welding parameters for TIG welding is performed as described in Section 6, Parameter settings.

#### 5.1.1 Electrode welding

The settings for electrode welding is performed as described in Section **Fehler! Verweisquelle konnte nicht gefunden werden..**

The electrode is simultaneously the arc carrier and the additional material. It consists of an alloyed or non-alloyed core wire and a coating. The coating has the task of protecting the weld pool from the harmful ingress of air and stabilizing the arc. It also forms slag, which protects and forms the weld seam. Electrode welding can be used to weld almost all metals. Electrode welding is a common, easily handled welding process.



When setting up for electrode welding care must be taken that no TIG torch is fitted. If this is not the case the digital display shows the error number "E021" (see Section 14.3)

#### 5.1.2 Electrode BOOSTER function

The settings for the electrode welding BOOSTER is performed as described in Section 6.

In this mode the power supply fuse monitoring is switched off. The maximum welding power emitted by the "TIGER DIGITAL 180" is 150A and with "TIGER DIGITAL 230" 180A. If a higher setpoint is selected, this is automatically reduced to 150A or 180A.



When setting up the booster function care must be taken that no TIG torch is fitted. If this is not the case the digital display shows the error number "E021" (see Section 14.3)

## 5.2 Corner menu operating mode (top right)

The menu Operating modes [BF3] is activated by pressing the button at the top right of the keypad Fig.8. This allows the selection of the operating modes

1. 2 cycle with HF ignition (see Section 5.3)
2. 4 cycle with HF ignition (see Section 5.3)
3. 2 cycle without HF LiftArc
4. 4 cycle without HF LiftArc
5. Spot
6. Interval

Functions may be limited depending of the equipment features.

### 5.2.1 2 cycle operating mode

The 2 cycle mode is recommended for fast, controlled tacking and manual spot welding.

- 1. cycle: Actuate the torch trigger

The protective gas solenoid valve opens

After the set gas pre-flow time has expired the arc is ignited

The welding current automatically adjusts to the selected slope-up time, starting from the set starting current and rising to the preselected value for  $I_1$ .

- 2. cycle: Release the torch trigger

The current reduces to the set end crater value at the preselected current slope-down time and then automatically switches off.

The inert gas flow is according to the selected gas post-flow value.

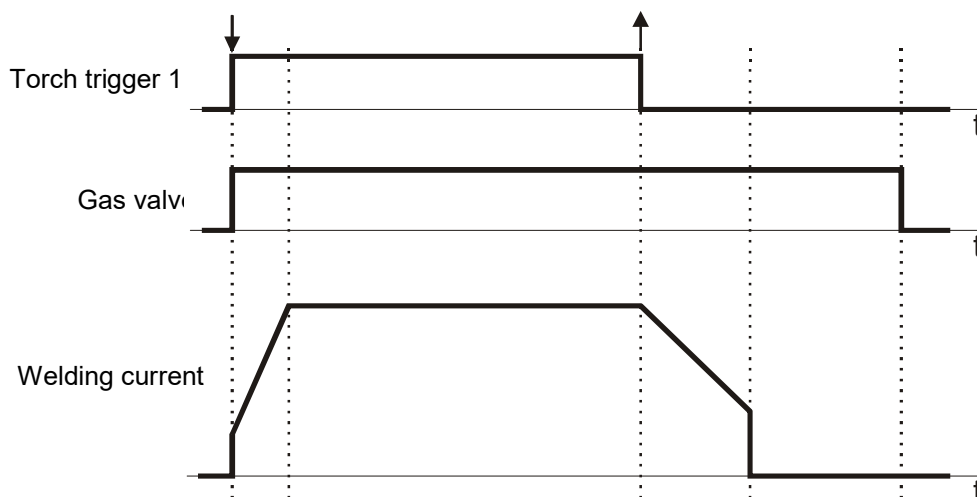


Fig.10 Process for 2 cycle welding

Peculiarities:

to the 2nd cycle

Actuating the torch trigger a second time during slope-down of the welding current jumps the welding current back to  $I_1$ . This process is also known as manual pulsing (see Section 6.1.9). Actuating the torch trigger 2 (BT2) extinguishes the arc.



### 5.2.2 4 cycle operating mode

In the 4 cycle operating mode the need to permanently actuate the trigger is omitted, enabling the torch to be guided for a longer period without fatigue.

Sequence of the 4 cycle operating mode:

- 1. cycle – operate the torch trigger

The protective gas solenoid valve opens

After the set gas pre-flow time has expired the arc is ignited

The welding current is at the value set for the starting current

- 2. cycle: Release the torch trigger

The welding current automatically reaches the preset values for  $I_1$  after the selected slope-up time.

- 3. cycle: Actuate the torch trigger

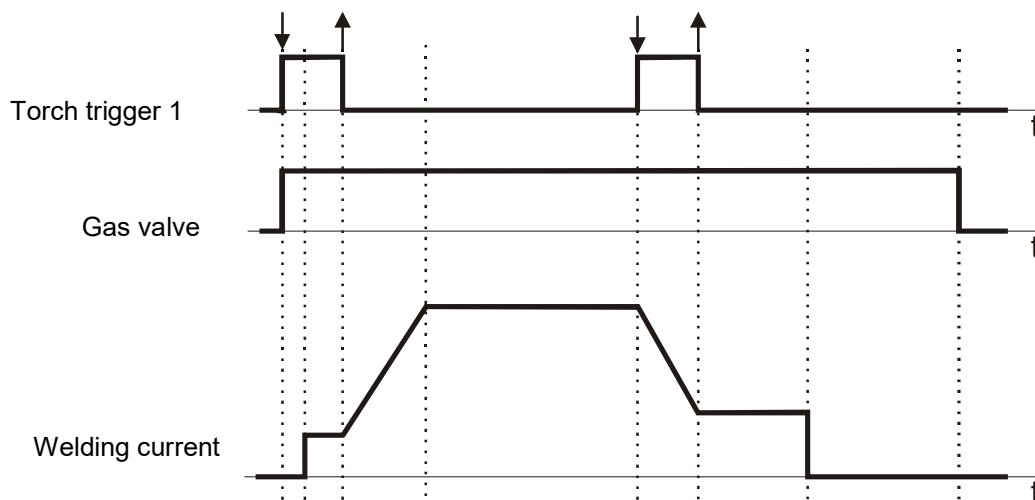
The current reduces to the set end crater value at the preselected current slope-down time.

The welding current flow is at the set end crater value

- 4. cycle: Release the torch trigger

The arc extinguishes

The inert gas flow is according to the selected gas post-flow value.



**Fig.11 Process for 4 cycle welding**

to the 2nd cycle Actuating the torch trigger a second time during slope-up of the current extinguishes the arc and the protective gas continues to flow according to the selected gas post-flow time.

to the 3rd Cycle The arc can be switched off during the slope-down period. Releasing the torch trigger before reaching the end crater current extinguishes the arc and the protective gas continues to flow for the set post flow time.

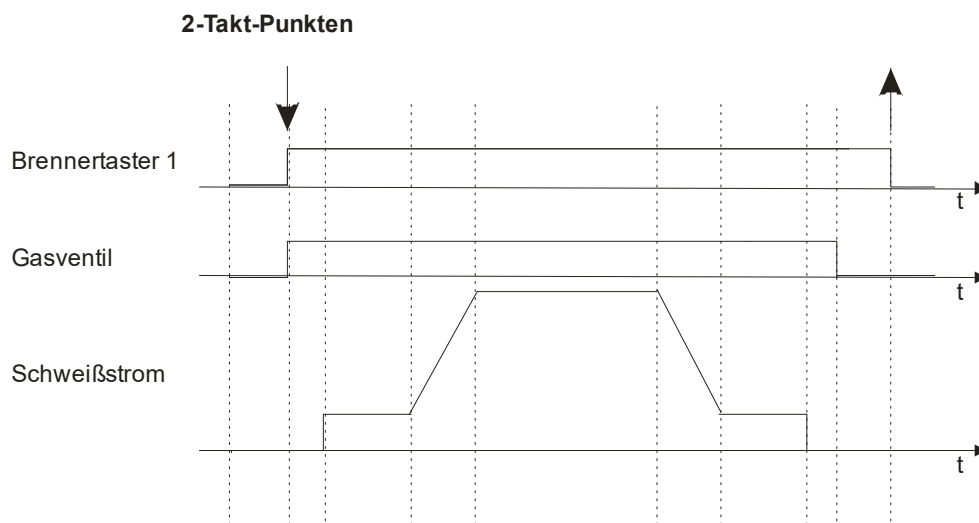
### 5.2.3 TIG spot welding

The spot welding mode is recommended for welding with a fixed spot welding time from 0.01 seconds.

The stationary welding process runs with a fixed spot welding time, unless the trigger is released prematurely during the welding.

The program runs to the end after expiry of the set spot welding time or after releasing the torch trigger during the welding.

The lower heat input into the materials being welded enables TIG welding with low distortion and only slight discolouration.



**Fig.12 TIG spot welding**

- 1. cycle Operate the torch trigger

The set gas pre-flow time expires, the gas valve opens. After the gas pre-flow time has expired the arc is ignited. The welding current automatically adjusts to the starting current. After expiration of the current slope-up time the welding current reaches the preselected value  $I_1$ . The set spot welding time expires. After the spot welding time expires the current reduces according to the preselected slope-down time to the value set for the end crater current and automatically switches off after expiry of the end current time.

- 2. cycle Release the torch trigger

The inert gas flow is in accordance with the selected gas post-flow value.

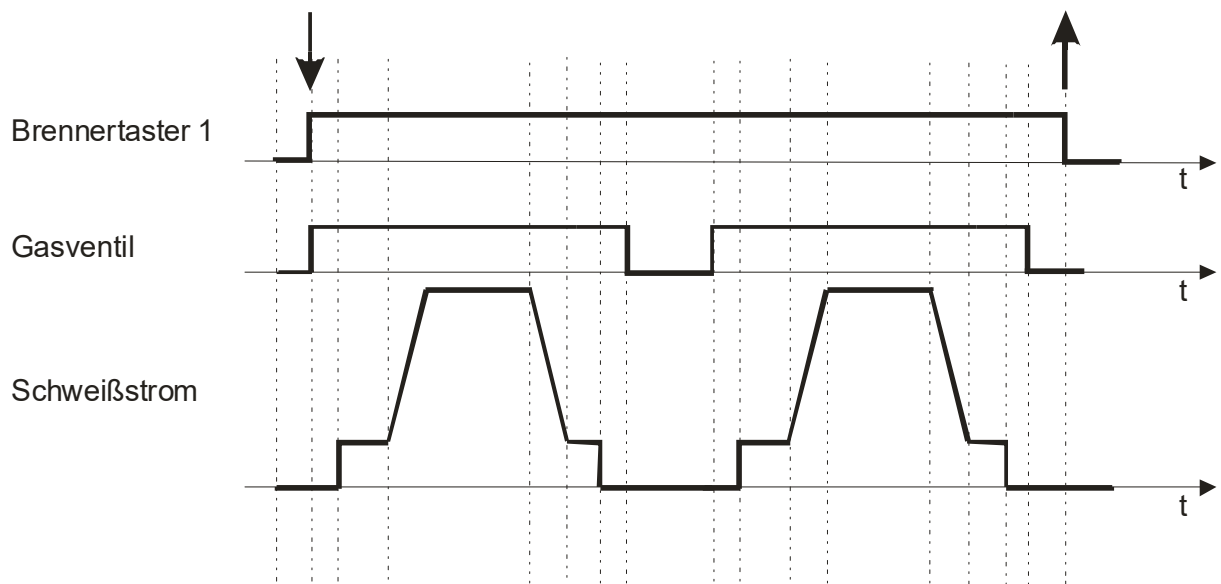
#### 5.2.4 TIG interval

Interval welding is defined as spot welding with defined pause times. This makes possible the application of the thinnest filler material.

Interval welding is only possible in the 2 cycle operating mode.

Welding in the interval welding mode is recommended for welding with a fixed break welding time from 0.01 seconds.

In TIG interval mode the pause time between the single intervals can be adjusted and the cooling of the base material guaranteed, which means less warpage.



**Fig.13 Process for 2 cycle interval**

- 1 cycle: Actuate the torch trigger  
The set gas pre-flow time expires, the gas valve opens. After the gas pre-flow time has expired the arc is ignited.  
The welding current automatically adjusts to the starting current. After expiration of the current slope-up time the welding current reaches the preselected value I1. The set interval welding time expires.  
After the interval welding time expires the current reduces according to the preselected slope-down time to the value set for the end crater current and automatically switches off after expiry of the end current time, i.e. the welding current goes to 0A. The inert gas flow is according to the chosen gas post-flow time, and the pause time.  
The welding current then reverts to the preselected starting current and the welding process continues as described.
- 2 cycle: Release the torch trigger  
Interval welding ceases.

## 5.3 High-frequency (HF) ignition

The corner button operating modes [\[BF3\]](#) is used to activate the 2 and 4 cycle processes with HF ignition.

### 5.3.1 Welding with HF ignition

REHM TIG welding machines are equipped with RF igniter. HF ignition is automatically switched off in the "electrode" setting.

HF ignition makes contact-free ignition of the arc between the electrode and workpiece through pre-ionization of the air gap for DC and AC welding possible, whereby tungsten inclusions and therefore welding defects are prevented. In either case, the HF ignition unit is automatically switched off again after ignition. Re-ignition of the arc described in Section 6.2.2 when AC welding is performed without using the HF ignition unit. This reduces the electrical noise emission and

even enables AC welding without HF ignition, as is already known for DC welding (see Section 5.3.2).

The RF igniter is operational when set to RF On "1". To ignite the arc, the electrode is kept approx. 3-5 mm above the workpiece. By actuating the torch trigger the path is ionized by a high-voltage pulse and arcing occurs. Contactless ignition enables the prevention of tungsten inclusions in the welded seam. When welding the HF ignition is automatically switched off after ignition.

### **5.3.2 Welding without HF ignition**

When welding with direct or alternating current contact ignition (LiftArc ) can be used. For this the high frequency is turned off. To ignite the arc, the electrode is placed on the workpiece and the torch trigger actuated. On lifting the electrode the arc program-controlled ignition takes place without wear occurring to the pointed electrode. This option can be used to advantage when working on sensitive electronic devices (for example, in hospitals, repair welding on CNC machines), where there is the risk of interference originating from high voltage pulses.

## 5.4 Corner menu welding process (bottom right)

The corner menu welding process [BF4] is used to select:

- Time pulses
- Hyper-Pulsen®
- Pulse off

### 5.4.1 Time pulses

#### Pulses with pulse times from 0.5 to 5.0 seconds

The setting of the I1-pulse time t1 and the I2-pulse time t2 determines the duration that current I1 or current I2 remains active until switching to the other current. Both pulse times can be set independently of each other.

The times and welding current peaks should be matched so that the base material is melted during the high current phase and solidified during the low current phase. In difficult situations (particularly in out of position welding and large gap bridging) and with thin sheet welding TIG pulse welding enables the weld pool to be controlled better than with constant welding current.

### 5.4.2 Hyper pulses

#### Pulses with a pulse frequency of 10 Hz to 15 kHz.

The flow of the welding current is the same as conventional pulsing. However, the periods during which current I1 and I2 are active are always the same. As this period is very small a description with pulse frequency is expedient and customary.

The following correlations apply for the conversion of the pulse frequency for the each of pulse time t1 and t2:

$$\begin{aligned}\text{Total pulse time} &= \text{I1 pulse time t1} + \text{I2-pulse time t2} = 1 / \text{pulse frequency} \\ \text{I1 pulse time t1} &= \text{I2-pulse time t2} = 0.5 * \text{total pulse time}\end{aligned}$$

Example:

Pulse frequency = 50 Hz

$$\text{Total pulse time} = \text{I1 pulse time t1} + \text{I2-pulse time t2} = 1 / 50 \text{ Hz} = 20 \text{ ms} = 0.02 \text{ s}$$

$$\text{I1-pulse time t1} = 0.5 * \text{total pulse time} = 0.01 \text{ s}$$

$$\text{I2-pulse time t2} = 0.5 * \text{total pulse time} = 0.01 \text{ s}$$





This means that the current when welding has the value current I1 for 0.01 s (= 10 ms), then for 0.01 s (= 10 ms) the value current I2, then once again for 0.01 s (= 10 ms) the value current I1, etc.

Pulses of such short duration bring about a more narrow and concentrated arc and deeper penetration.



## 5.5 Corner menu polarity (bottom left)

The bottom left corner button (**Fig.7 Corner function buttons**), is used to select the polarity:

• Alternating current (AC)	
• Dual Wave	
• DC positive pole	
• DC negative pole	

After exiting the menu, the selected polarity is displayed in the corner button field 5, **Fig.9**.



When electrode welding it must be noted that on all TIGER DIGITAL DC welding systems the left output socket is always negative.

Insert the electrode holder in the output socket in accordance with the electrode manufacturer's instructions and adjust.

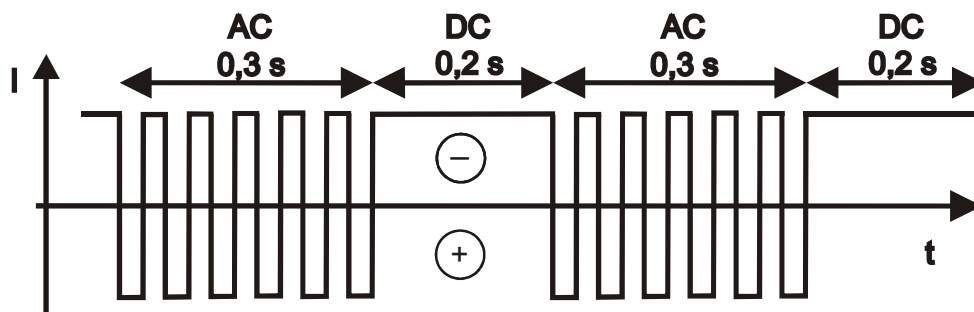
### 5.5.1 Alternating current (~)

When AC welding the polarity at the output terminals is constantly changing back and forth between positive and negative polarity. When TIG welding the torch is normally connected to the left output socket. The use of alternating current enables the welding of aluminium and aluminium alloys.

### 5.5.2 Dual Wave (=/~)

The Dual Wave process from REHM is a combination of AC and DC welding. When welding this is automatically set by the processor controller at 0.2 seconds DC and then 0.3 seconds AC. The selected values for the welding current  $I_1$  or  $I_2$ , the frequency and the balance are taken into account for purely DC or AC welding.

The Dual Wave process enables better control of the weld pool and is used in difficult welding positions, when welding workpieces of different thicknesses and in the processing of thin sheets of aluminium and aluminium alloys.



**Fig.14** Welding current process with the dual-wave

### 5.5.3 DC positive positive pole (+)

In TIG welding with positive pole the plus pole is applied to the left output socket for the TIG torch.

In DC TIG welding the positive electrode is subject to a very high thermal load, which can result in the electrode melting and damage even at low current.

When electrode welding with plus pole the electrode holder is also connected to the left output socket. When setting the DC positive electrode welding is performed with the electrode as the positive pole.

When electrode welding the polarity selected for the electrode depends on the type of electrode being used (observe the electrode manufacturer's instructions).

#### **5.5.4 DC negative pole (-)**

In TIG welding with negative pole the negative pole is applied to the left output socket for the TIG torch. TIG welding with direct current is usually welded with this set-up.

When electrode welding with negative pole the electrode holder is also connected to the left output socket. The electrode is welded with negative polarity.

When electrode welding the polarity selected for the electrode depends on the type of electrode being used (observe the electrode manufacturer's instructions).

## 6 Parameter settings

The selection and processing of the welding parameters is carried out for the most part directly in the illustrated welding wave using the push and rotate encoder [Fig.8].

The representation and setting options depend on the device type and the preselected welding process.

The default position of the cursor (pointer) is the current value I1. The cursor automatically jumps to this position if it is not actuated for a short time.

The cursor can be moved clockwise or counter clockwise. The main display always shows the value and function of the cursor position.

### 6.1 Setting the TIG welding parameters

For processing, a parameter field is activated by rotating the rotary encoder [BF5] to the adjustable value field [parameter field] in the screen display and activating this field by pressing the encoder. The background colour of the field changes (is highlighted).

If the parameter field is active, the set value appears as a large display in the main display field [BF2] Fig.9 item 2 of the screen.

In addition, a bar display appears in the status field Fig.9 item 9, which shows the set value in the permissible value range.

Below the welding parameters are detailed in the order according to the parameter curve TIG welding [BF6].

#### 6.1.1 Gas pre-flow time

The gas pre-flow time is the period of time after activating the torch trigger of torch to start the welding process and the opening of the protective gas valve before the arc is ignited. Then the arc is ignited in the protective gas mantle, whereby the electrode and the workpiece is protected from burning out.

If the welding process is restarted during the gas post flow time, then the gas pre-flow time is automatically set to 0 seconds by the processor control. This speeds up the reignition, which helps to save time.

#### 6.1.2 Ignition power

The ignition energy can be infinitely adjusted between 10 and 100% when igniting for high-frequency or LiftArc.

The processor control always sets a preselection for the required ignition process irrespective of the value selected for ignition energy.

This preselection can be adapted to the particular electrode (type and diameter) and the respective welding task by adjusting the ignition energy.

A low ignition energy should be selected when welding thin material and with small electrode diameters.

With AC welding systems from an ignition energy setting of 90% a "power ignition" is performed, whereby ignition is facilitated in harsh environments.

### 6.1.3 Starting current

The starting current is the welding current that is first set after the ignition process. The setting is infinitely variable between 10% and 200% of the selected welding and pulse current  $I_1$ .

The value range is limited by the maximum unit flow.

Example: Start current 40% and welding current  $I_1$  100A  
results in a start current of 40A.

The adjustment of the starting current allows:

- A reduction of the electrode load by a gradual increasing of the current.
- A search arc for 4 cycle welding for approaching the start of the seam
- Reduction of heat input  
at the beginning of the seam for edges or sires of heat accumulation.
- An increase in heat input  
at values above 100%

### 6.1.4 Slope-up time

The current slope-up time is the period in which the welding current increases linearly from the start current to the preselected welding current  $I_1$ .

During 2 cycle welding the current slope-up time begins immediately after the arc is ignited.

During 4 cycle welding the slope-up time begins with the release of the torch trigger with the start of current phase.

### 6.1.5 Welding current $I_1$ and pulse time $t_1$

The setting range for welding or pulse current  $I_1$  depends on the selected mode and type of machine.

### 6.1.6 Welding current $I_2$ and pulse time $t_2$

The use of welding current  $I_2$  only makes sense with TIG welding and therefore is only displayed when TIG welding.

Welding current  $I_2$  is used for pulsing (see Section 6.1.5) and for twin-current control:

#### **Twin-current control:**

With twin-current control the user can work with 2 different, pre-set currents when using a torch with 2 triggers. Its possible to switch between the two values  $I_1$  and  $I_2$  during welding.

Switching to  $I_2$  is effective for as long as torch trigger 2 is actuated. When released the system immediately switches back to  $I_1$ .

Switching example:

- From high-current to low-current or vice-versa, for example when changing the welding position.
- Manual pulsing (see Section 6.1.9)
- Starting at high current  $I_1$  for warming the workpiece, then welding with low-current  $I_2$
- Starting with low-current  $I_1$  at an edge on the workpiece, then welding with high-current  $I_2$ .

Switching is possible in both 2 and 4 cycle modes without pulsing.



The current  $I_2$  is set either by activating the setting option  $I_2$ , or also very quickly and easily by actuating torch trigger 2 before the welding process. When the torch trigger 2 is held down the current value  $I_2$  is shown in the digital display and can be altered by turning the rotary encode.

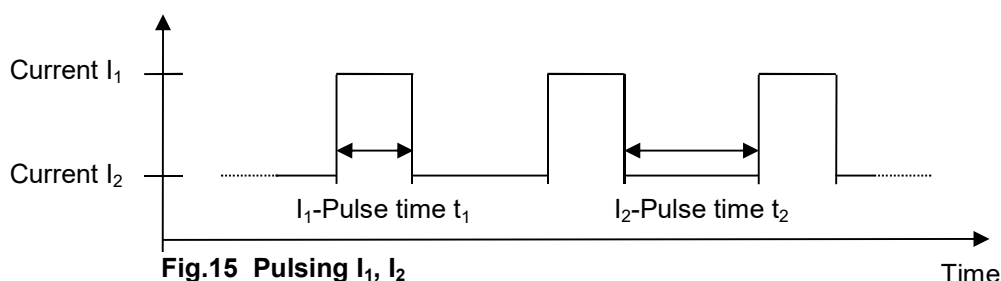
### 6.1.7 Automatic pulsing

TIG welding with the pulse function can be basically divided into two areas:

1. **Time pulsing** with pulse times between 0.1 and 0.5 seconds
2. **Hyper pulsing** with pulse frequencies between 10 Hz and 17.5 Hz.

With pulse welding switching between the currents  $I_1$  and  $I_2$  occurs during the welding process. Switching is performed automatically according to the set pulse times  $t_1$  and  $t_2$ .

The currents  $I_1$  and  $I_2$  can be freely set, so that in deviation to the representation **Fig.15** alternative  $I_2$  can result in a higher pulse current.



**Fig.15 Pulsing  $I_1, I_2$**



During welding the pulse can be switched off and switched back on by actuating the torch trigger 2.

If torch trigger 2 is actuated during pulsing welding current the pulses are switched off and welding continues with welding current  $I_2$ .

As an example, this can be used so that the lower welding current  $I_2$  is used until a new additional material has taken hold and the welding is continued with pulsing welding current by actuating the torch trigger 2 a second time.

#### **Conventional pulsing: Pulses with pulse times from 0.5 to 5.0 seconds**

The setting of the  $I_1$ -pulse time  $t_1$  and the  $I_2$ -pulse time  $t_2$  determines the duration that current  $I_1$  or current  $I_2$  remains active until switching to the other current. The actual output welding current is always shown on the indicating instrument.

The times and welding current peaks should be matched so that the base material is melted during the high current phase and solidified during the low current phase. In difficult situations (particularly in out of position welding and large gap bridging) and with thin sheet welding TIG pulse welding enables the weld pool to be controlled better than with constant welding current.

#### **High frequency pulsing: with a pulse frequency of 10 Hz to 17.5 Hz.**

The flow of the welding current is the same as conventional pulsing. However, the periods during which current  $I_1$  and  $I_2$  are active are always the same. As this period is very small a description with pulse frequency is expedient and customary.

The following correlations apply for the conversion of the pulse frequency for the each of pulse time  $t_1$  and  $t_2$ :

$$\text{Total pulse time} = I_1\text{-pulse time } t_1 + I_2\text{-pulse time } t_2 = \frac{1}{\text{pulse frequency}}$$

$$I_1\text{-pulse time } t_1 + I_2\text{-pulse time } t_2 = 0.5 * \text{total pulse time}$$

Example:

Pulse frequency = 50 Hz

Total pulse time =  $I_1$ -pulse time  $t_1$  +  $I_2$ -pulse time  $t_2$  =  $1 / \text{Hz} = 20 \text{ ms} = 0.02 \text{ s}$

$I_1$ -pulse time  $t_1$  =  $0.5 \cdot \text{total pulse time} = 0.01 \text{ s}$

$I_2$ -pulse time  $t_2$  =  $0.5 \cdot \text{total pulse time} = 0.01 \text{ s}$

This means that the current when welding has the value current  $I_1$  for 0.01 s (= 10 ms), then for 0.01 s (= 10 ms) the value current  $I_2$ , then once again for 0.01 s (= 10 ms) the value current  $I_1$ , etc.

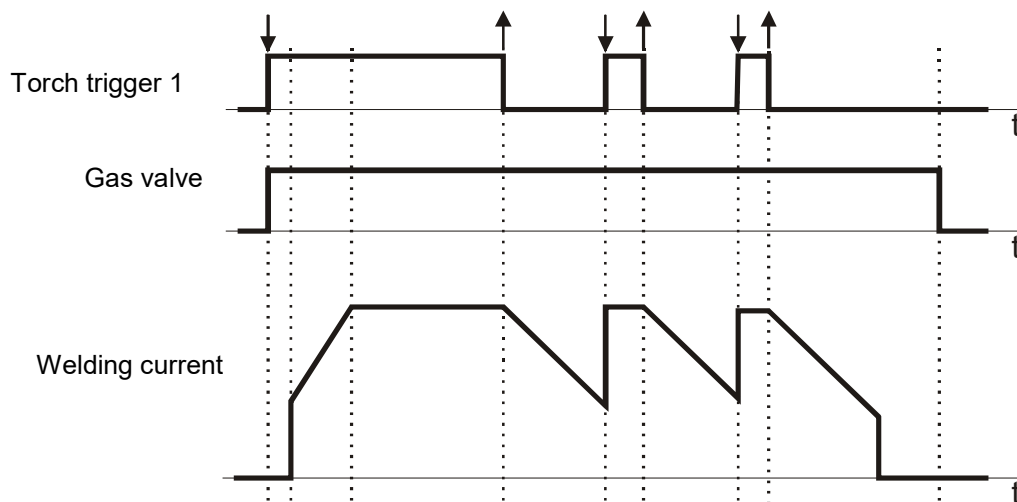
Pulses of such short duration bring about a more narrow arc and deeper penetration.

The current average value is always shown in the main display field because of the rapid alternations. This means that for welding current  $I_1 = 100 \text{ A}$  and  $I_2 = 50 \text{ A}$  the indicator shows 75A.

### 6.1.8 Manual pulsing



If, with the TIG 2 cycle function, torch trigger 1 is actuated during the slope-down time, then the welding current immediately jumps to the value used for welding. The average energy is infinitely variable and can be directly selected depending on the time at which the torch trigger is actuated during slope-down.



**Fig. 16: Flow diagram Manual Pulse**

### 6.1.9 Slope-down time

The current slope-down time is the period in which the welding current decreases linearly to the end-crater current. With 2 cycle welding the current slope-down time begins immediately after release of torch trigger 1.

With 4 cycle welding the slope-down time begins during welding with the actuation of torch trigger 1. The slow slope-down of the welding current prevents the occurrence of end craters.

### 6.1.10 End crater current $I_e$

The end crater current is the welding current to which the welding current is reduced when the welding process is ended. The setting is infinitely variable between 10% and 100% of the selected current  $I_1$  (for example:

Example: End crater current 40% and welding current  $I_1$  100A  
results in an end crater current of 40A.

Selecting the appropriate end crater current enables:

- Prevention of notches and end crater cracks at the end of the weld seam due to rapid cooling of the weld pool
- Manual pulsing (see Section 6.1.9)
- Welding with reduced current at the end of the weld seam at edges or for heat accumulation

#### **6.1.11 Gas post flow time**

The gas post flow time is the time after the arc extinguishes before the protective gas valve closes.

The post flow of protective gas protects the workpiece and the tungsten needle from attack by oxygen in the atmosphere until they have cooled down. The pre-selected gas post flow time is, however, only effective when welding has taken place. The accidental actuation of the torch trigger does not result in the running of the gas post flow. This gas management function reduces gas consumption.

## 6.2 AC settings menu

The [AC settings menu \[BF7\]](#) is only visible on AC devices.

Depending on the equipment variant, further functions are restricted, ([Table 2](#)).

### 6.2.1 AC waveform

Selection between sinus, rectangle and triangle waveforms.

In the **Auto** setting, the waveform is set automatically.

### 6.2.2 AC frequency (Hz)

The frequency value determines how fast the output polarity reversal takes place one after the other. The setting range extends from 30 Hz to 300 Hz.

For example, at a frequency of 200 Hz the polarity reversal at the output socket from plus to minus and back occurs every 5ms (=0.005 seconds).

The welding current drops to zero with every polarity reversal, ignites again in the opposite direction and increases to the set welding current.

The adjustable frequency when AC welding, results in a considerable noise reduction and improvements in the alternating current welding.

The REHM patented automatic frequency control can be selected as a special feature for TIG AC current welding.

The frequency is set to "Auto" for activation.

The automatic frequency control developed by REHM combines the benefits of a very stable arc in the lower welding current range with the benefits of a high electrode capacity in the high current range.

The AC frequency is automatically adjusted to the actual momentary value of the welding current.

Normally, the selection of automatic frequency control makes setting the frequency superfluous. This setting option provides unlimited flexibility other than a few special application-specific cases where it is desirable to use a frequency that is different to that selected by the automatic frequency control.

### 6.2.3 AC balance ( )

The AC balance setting option is only available with AC current welding with TIG. It ranges from -5 to +5 and enables the arc to be influenced as well as the penetration and cleaning when welding aluminium over a very large range.

In the centre position (0) the negative and positive welding current is equally distributed over time.

With an increasing positive value the share of the positive welding current increases (up to +5) and the negative share reduces. The cleaning of the weld pool is improved by the positive share. The arc is wider and heat penetration less deep.

With an increasing negative value the share of the negative welding current increases (up to -5) and the positive share reduces. This makes the arc more narrow and generates a deeper weld penetration at the same time as a low electrode load.

The use of the highest possible negative value whilst maintaining a sufficient cleaning effect is recommended.

### 6.2.4 Further settings for DualWave

The AC setting menu [\[BF7\]](#) is augmented by the setting options for



AC time: During this time the unit welds in the AC mode set above  
 DC time: Her in DC mode.

The Dual Wave process from REHM is a combination of AC and DC welding. The selected values for the welding current  $I_1$  or  $I_2$ , the frequency and the balance are taken into account for purely DC or AC welding.

## 6.3 Menu spot welding and interval

### 6.3.1 Spot time

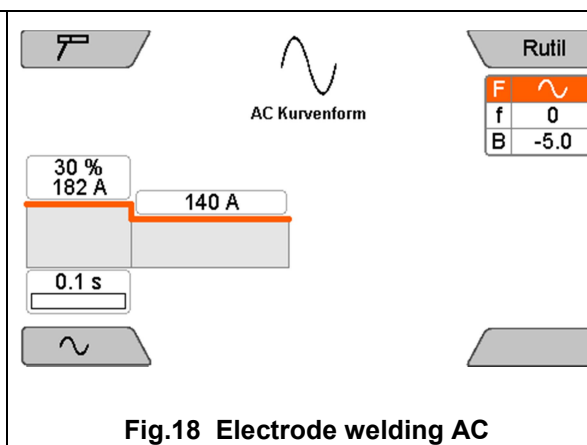
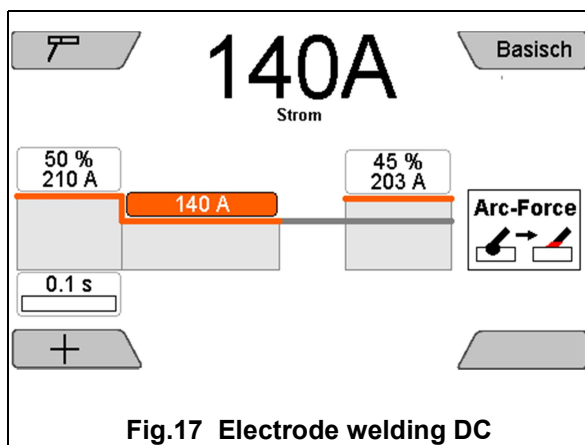
The setting menu spot welding time [BF8] appears when the spot welding function is selected in the corner menu [BF3]. The spot welding time can be set in the range 0.01s to 30.0s.

### 6.3.2 Pause time

The setting menu spot, pause time [BF8] appears when the interval welding function is selected in the corner menu [BF3]. The spot welding time can be set in the range 0.01s to 30.0s.

## 6.4 Electrode welding parameters

When the electrode welding is set, the TIG welding curve is reduced to the electrode representation and to the corresponding adjustment possibilities.



#### 6.4.1 Setting options (from left to right)

Function	Setting	Ultra AC/DC	Ultra DC	High AC/DC	High DC
Hotstart current	In % over welding current	✓	✓	—	—
Hotstart time	0.1 to 10s	✓	✓	—	—
Welding current	20A ... I <sub>max</sub>	✓	✓	✓	✓
ArcForce	0 ... 300%	✓	✓	—	—
<b>Corner menu bottom left</b>					
DC negative		✓	✓	✓	✓
DC plus		✓	✓	✓	✓
AC	ArcForce nor possible	✓	—	✓	—
<b>Additional menu AC</b>					
Waveform	only Sinus possible	✓	—	✓	—
Frequency	Auto or 30 ... 150Hz	✓	—	✓	—
Balance	-5.0 ... +5.0	✓	—	✓	—
<b>Corner menu (top right)</b>					
Basic		✓	✓	✓	✓
Rutile		✓	✓	✓	✓



When setting up for electrode welding care must be taken that no TIG torch is fitted. If this is not the case the display screen shows the error number "E021".

#### 6.4.2 Hot Start

When electrode welding, a higher current than the set welding current I<sub>1</sub> is used for a short time when starting welding to achieve better electrode ignition. The set hot start determines its magnitude. Using the push and rotary encoder, the setting is infinitely variable between 0% and 200% of the selected current I<sub>1</sub> limited to the maximum unit current

#### 6.4.3 Welding current I<sub>1</sub>

The welding current I<sub>1</sub> can be continuously adjusted up to the maximum value specific to the unit.

TIGER DIGITAL 230	TIGER DIGITAL 180
3 A ... 180 A	3 A ... 150 A

#### 6.4.4 ArcForce

For a stable arc during electrode welding, it is important to support a droplet-shaped material transfer through very short current pulses overlaid to the selected welding current I<sub>1</sub>.

The magnitude of these current pulses is determined by the selected ArcForce setting.

In both of the electrode types that can be selected, rutile and basic, the value can be set stepless between 0% and 300%.

Example: ArcForce 50% and welding current I<sub>1</sub>=100A  
This results in a current pulse of 150A

#### **6.4.5 Anti-stick-automatic**

If a permanent short-circuit is present during electrode welding, then after 0.3s the ant-stick function initiates and limits the current to approximately 20A. This prevents the electrode from glowing and the permanent short circuit can be solved easily by pulling out.

## 7 Submenus

Pressing the "List submenus" button [BF10] accesses a selection list (drop down list) for the existing submenu.

The following menus can be selected from this list:

1. Language selection
2. Assist
3. Save and load programs
4. Special parameters (setup)
5. Error messages and error memory

The submenus can be exited in 3 ways, with the return button [BF11]:

1. One level back by acknowledging a setting
2. One level back by pressing the **"Back"** button
3. Completely back to the main screen with the button **"Main menu"** (Rehm or Home).

### 7.1 Language menu

The available languages are displayed as flags in a selection list.

Use the cursor to select a language and confirm by pressing the rotary encoder.

The language becomes active immediately.

The selected language is illustrated by a box with cross.

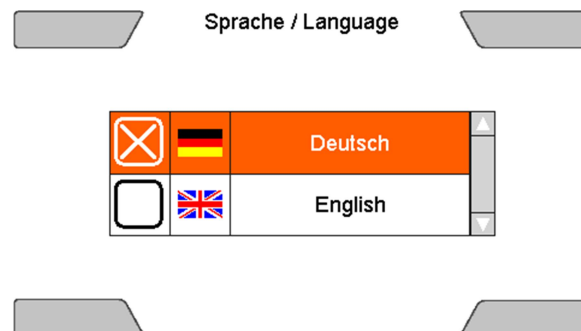


Fig.19 Submenu language selection

### 7.2 Assist

The Assist submenu is an assistant program that provides help with welding settings for specific welding tasks.

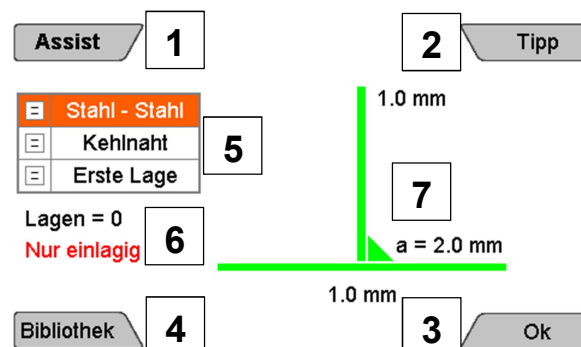


Fig.20 Main screen Assist

<b>Corner menu</b> <b>1</b>	
Assist	Indicates that you are in Assist
<b>Corner menu</b> <b>2</b>	
Tip	<p>Display and recommendations for the welding task other than the TIG or electrode settings:</p> <ul style="list-style-type: none"> <li>• Number of positions</li> <li>• Type of gas</li> <li>• Gas flow rate</li> <li>• Gas nozzle size</li> <li>• Preheat temperature</li> <li>• Diameter of filler material</li> <li>• Electrode type</li> <li>• Electrode diameter</li> <li>• Grinding angle</li> <li>• ...</li> </ul>
<b>Corner menu</b> <b>3</b>	
OK	<p>Accept settings</p> <p>The message "Accepted" appears in the status window</p>
<b>Corner menu</b> <b>4</b>	
Library	<p>Submenu Additional information:</p> <ul style="list-style-type: none"> <li>• TIG electrodes</li> <li>• Filler materials</li> <li>• Gases</li> <li>• Welding positions</li> </ul> <p>The folder can be searched when the library folder is opened by rotating and pressing the <b>Fig.8</b> encoder. Return with the "Back" button.</p>
<b>Screen settings</b> <b>5</b>	
Material	<p>Available options:</p> <ul style="list-style-type: none"> <li>• AL - AL</li> <li>• Steel - Steel</li> <li>• Steel - CrNi</li> <li>• CrNi - CrNi</li> </ul>
Weld shape	<p>Available options:</p> <ul style="list-style-type: none"> <li>• Butt weld</li> <li>• Fillet weld</li> </ul>
Position	<p>Available options:</p> <ul style="list-style-type: none"> <li>• First position</li> <li>• Further positions</li> </ul>
<b>Screen display</b> <b>6</b>	
Position	Display positions 1, 2, ...

<b>Workpiece view</b>	<b>7</b>
Workpiece	<p>Select the workpiece with the rotary encoder, confirm by pressing and set the material thickness.</p> <p>Displays:</p> <ul style="list-style-type: none"> <li>- Material thickness</li> <li>- Grinding angle (only with butt seam)</li> <li>- A dimension (only for fillet welds)</li> <li>- Required number of layers</li> </ul> <p>Alerts: An alert is given for inapplicable settings.</p>

## 7.3 Save and load programs

### 7.3.1 Quick program buttons P1 ... P4

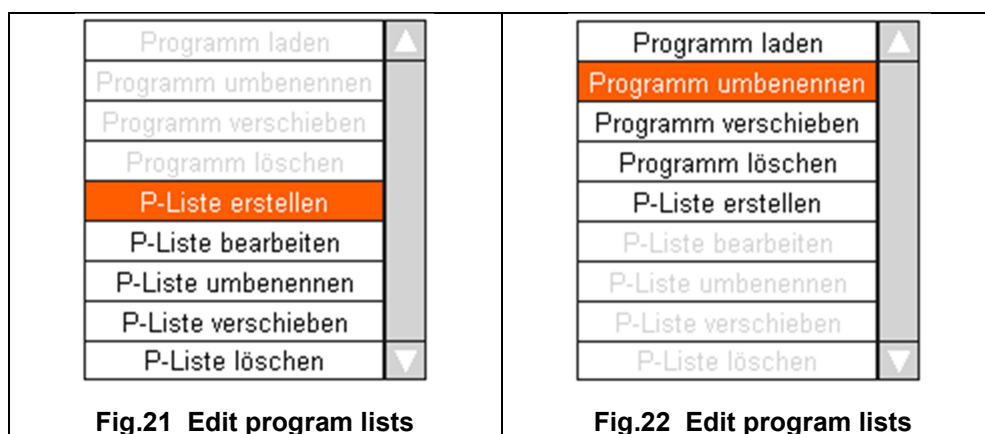
Buttons P1 to P4 (**Fig.4**) are used to call welding specific settings (see section 5 and 6) by pressing the P button and to save specific settings by holding the P button for a minimum of 2 seconds.

After active welding (torch button 1 pressed) the active device configuration remains stored after power off and is available as soon as the unit is restarted.

The memory location for the fast program buttons for programs 1 to 4 is a total of 99 programs in the subprogram.  
These cannot be overwritten or edited there.

### 7.3.2 Memory programs 5 to 99

Programs lists and programs can be edited in the submenu Programs:



Program lists are equivalent to folders. A total of 99 programs can be managed in a maximum of 99 parameter lists.

The directory name is freely selectable (for example, the name of an employee, a customer or the material to be processed).

Therefore, once the unit settings are determined for recurring welding tasks they can be recalled at the welding units in seconds. This saves time and ensures consistent quality.

The individual welding unit base settings such as the start and end crater current, ignition energy, etc., for use by multiple people can be saved for each person and quickly duplicated.

### 7.3.3 Manage parameter lists (folders)

Initially, the overview of the existing program lists appears in the program submenu, as shown in **Fig.25**.

If you select a program list, you can edit it using the corner menu (button at the bottom left next to the press/rotary encoder).

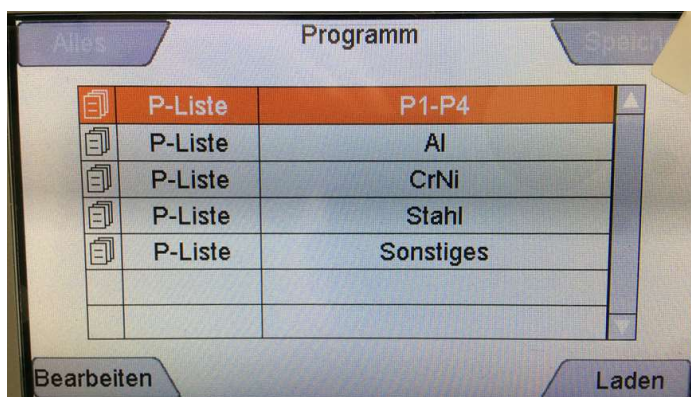


Fig.23 Actual P list screen section

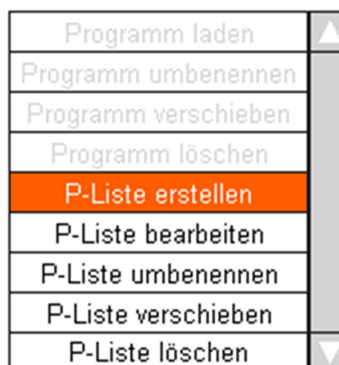


Fig.24 Edit menu program lists

#### Creating a new folder

In the submenu program lists

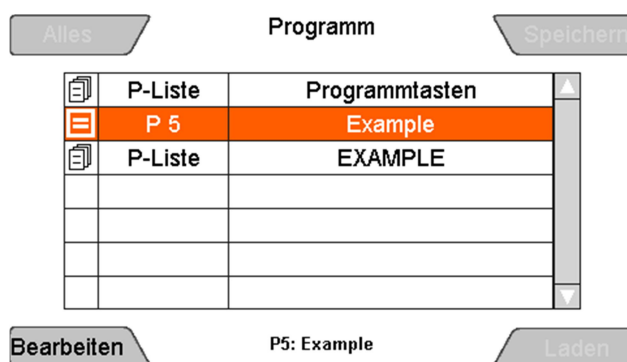


Fig.25 Submenu program lists

The following is a representative example of how to create a program list.

P-Liste erstellen															
Bitte legen Sie einen Namen für die P-Liste fest.															
EXAMPLE															

A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	▲
Q	R	S	T	U	V	W	X	Y	Z	Ä	Ö	Ü	1	2	3	
4	5	6	7	8	9	0	-	_	/		←	→	K	∞	ok	▼

Fig.26 Example creation of a P list



## 7.4 Optional water cooling unit

The TIGER DIGITAL can be equipped with the REHM water cooling unit as an option. The TIGER DIGITAL is connected to the water cooling unit with a plug-in connection cable with 9-pin plug (see fig. 27)

### Caution:


The REHM water cooling unit is only available in combination with the optional cooling unit connection. The cooling unit connection must be installed by REHM at the factory.

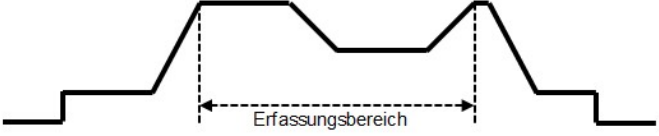


**Fig.27 TIGER DIGITAL with optional water cooling unit and cooling unit connection / rear view.**

## 8 Setup / special parameters

Setup		Diagnose	
Up-/Down Leerlauf	AC-Balance	<div>▲</div>	
Up-/Down Schweißen	AC-Balance		
Up/Down Geschwindigkeit	1		
Spannungsanzeige	Aus		
Wasserkühlgerät Modus	Aus		
E-Hand Polarität	Auto		
Brennerpoti	Aktiv		
Brennertaster 2	Taster 2-Takt		
Startstromanzeige	Ampere		
Gasfest			
Up/Down Idle	Adjustment possibilities from the torch using the UP / DOWN buttons when not welding: <ul style="list-style-type: none"><li>• Switch off UP/Down function (inactive)</li><li>• AC waveform</li><li>• AC frequency</li><li>• AC balance</li><li>• AC timeDualWave</li><li>• DC timeDualWave</li><li>• Switching between operating modes2/4cycle, ...</li><li>• End-crater current</li><li>• End-crater current time</li><li>• Gas post flow time</li><li>• Gas pre-flow time</li><li>• Switching <math>I_1 \leftrightarrow I_2</math> via BT2 0=switching operation: Off=<math>I_1</math>; ON=<math>I_2</math> 1=button operation: Each operation of the button toggles between <math>I_1/I_2</math></li><li>• Polarity</li><li>• Program selectionP1 ... P4</li><li>• Welding processPulse type</li><li>• Pulse time t1Conv. Pulse</li><li>• Pulse time t2Conv. Pulse</li><li>• Pulse frequencyHyper pulse</li><li>• Spot timeSpot welds</li><li>• Interval Pause timeInterval</li><li>• Welding processTIG, ...</li><li>• Starting current</li><li>• Starting current time</li><li>• Current <math>I_1</math>see line below</li><li>• Current <math>I_2</math>see line below</li><li>• Slope-up time</li><li>• Slope-down time</li><li>• Connecting HF ignition</li><li>• Ignition power</li></ul>		

Current $I_1$ and $I_2$	<p>Setting the welding current <math>I_1</math> and <math>I_2</math> with an up/down torch:</p> <ol style="list-style-type: none"> <li>1. Enable UP/Down torch The currents <math>I_1</math>, <math>I_2</math> can be controlled up or down before and during welding work.</li> <li>2. <math>I_1</math> can be adjusted using Up/Down</li> <li>3. <math>I_2</math> can be adjusted if is switched from <math>I_1</math> to <math>I_2</math> using torch button2 (see above).</li> <li>4. The same method is used to switch back</li> </ol> <p><b>During welding</b> the active currents <math>I_1</math> or <math>I_2</math> can be adjusted up and down at any time. If Up/Down is not actuated for 2 seconds, the system jumps back to</p> <p>During pulsed welding <math>I_1</math> is changed as a guide variable and <math>I_2</math> is changed in ratio. The percentage ratio of <math>I_2</math> to <math>I_1</math> is maintained in the case of a change of <math>I_1</math>. Selection of programs P1 and P2 with Up/Down torch</p>
UP/Down welding	<p>Adjustment possibilities from the torch using the UP/DOWN buttons when welding (torch button1 = BT1 active):</p> <ul style="list-style-type: none"> <li>• Switch off UP/Down function (inactive)</li> <li>• AC waveform</li> <li>• AC frequency</li> <li>• AC balance</li> <li>• AC time DualWave</li> <li>• DC time DualWave</li> <li>• Switching between operating modes 2/4cycle</li> <li>• End-crater current</li> <li>• End-crater current time</li> <li>• Gas post flow time</li> <li>• Manual switching between <math>I_1</math> and <math>I_2</math></li> <li>• Polarity</li> <li>• Program selection P1 ... P4</li> <li>• Pulse type/ Pulse form welding proc.</li> <li>• Pulse time t1 Conv. Pulse</li> <li>• Pulse time t2 Conv. Pulse</li> <li>• Pulse frequency Hyper pulse</li> <li>• Current <math>I_1</math> I-adjustment</li> <li>• Current <math>I_2</math> I-adjustment</li> </ul>
UP/Down speed	 <p>only if UP/Down is active</p>

Current display	<input checked="" type="checkbox"/> Aus <input type="checkbox"/> UI am Ende <input type="checkbox"/> UI, U am Ende	<p>0 Voltage indicator off</p> <p>1 Display of the average voltage after welding has stopped.</p> <p>2 Display of the average voltage</p> <p>- during welding</p> <p>- at the end of welding</p> <p>The average value is updated every 2 seconds.</p> <p>Voltage detection range:</p> 
Water cooling unit mode	<input checked="" type="checkbox"/> Aus <input type="checkbox"/> Ein <input type="checkbox"/> Auto	<p>ON OFF Auto</p> <p>Pump and fan are off</p> <p>Pump and fan are running</p> <p>Pump and fan are automatically switched on when welding or when the coolant temperature is greater than 30°C.</p>
Polarity electrode welding	<input type="checkbox"/> Manuell <input checked="" type="checkbox"/> Auto	Automatically sets to DC negative
Possibility to adjust the potentiometer from the torch	<input checked="" type="checkbox"/> Aktiv <input type="checkbox"/> Inaktiv	Potentiometer in the torch is active
Function torch button2 (BT2)	<input type="checkbox"/> Taster aus <input checked="" type="checkbox"/> Taster 2-Takt <input type="checkbox"/> Taster 4-Takt	BT2 mode of operation: On/Off button operation or 4 cycle
Start current display	<input type="checkbox"/> Prozentual <input checked="" type="checkbox"/> Ampere	
End current display	<input checked="" type="checkbox"/> Begrenzend <input type="checkbox"/> Rollierend	
Mode in the Program List menu (folder)		
Default position main screen	<p>If no settings are made, the cursor on the main screen automatically goes to current position I<sub>1</sub>. Factory setting is 20 seconds</p>	

## Factory settings

All settings (parameters) are reset to the factory settings. This does not affect: Special parameters and programs.



Welding parameters	Factory settings
Gas pre-flow time	0.1 s
Ignition current	50%
Starting current	50%
Slope-up time	0.1 s
Current I <sub>1</sub>	100 A.
Current I <sub>2</sub>	80 A.
Pulse time t <sub>1</sub>	0.3 s
Pulse time t <sub>2</sub>	0.3 s
Slope-down time	0.1 s
End-crater current	20%
Gas post flow time	5.0 s
AC frequency*	Automatic
AC balance*	0
Ignition	HF on
Operating mode	2 cycle
Polarity*	DC negative
EL current I <sub>1</sub>	150 A
Pulse type	Pulse off
Pulse frequency	500 Hz.
TIG spot welding	0.1 s
Electrode BOOSTER	Inactive

\* not used for DC system



## 9 Error memory

Meldungen				
#	Text	S-Zeit	B-Zeit	

Error message display

- Number of errors
- Error text
- Welding time
- Operating time

## 10 Indicating symbol

	The <b>REMOTE CONTROL</b> AKTIVE symbol [BF17] appears on the right of the status line [BF9] and indicates the remote controller as active.
	The control lamp BETRIEB Symbol [BF16] in green indicates that there is an open circuit voltage at the torch or electrode holder. The display is on the left in the status line. The same display in red indicates an overtemperature fault.
	The power section is switched off and there is no output voltage as long as this symbol is displayed. With TIG welding the gas post flow time runs when the power section is switched off. Once the unit has cooled the LED goes out and welding can commence automatically.

## 11 Accessories

### 11.1 Foot-actuated remote controller TIGER DIGITAL 180/230

REHM participants: 753 1051

The foot-activated remote controller TIGER DIGITAL 180/230 (see Section 17 - Accessories) can be used to match the welding current to the welding task during the welding work using the foot pedal. In doing so the current set at the machine is the current that is adjusted by actuating the pedal.

The foot-actuated controller is connected to the remote operating socket on the front side of the TIGER DIGITAL.

### 11.2 REHM TIG torch

The TIG torches (see Section 17 - Accessories) are matched to the TIGER DIGITAL electrical components. They offer many opportunities for remotely adjusting the current source (see Section 11.1, and 11.2). The use of other TIG torches with a remote control capability can result in functional faults or defects on the TIGER DIGITAL.

**CAUTION:**

**When TIG torches with remote control capability of any type that are not explicitly recommended by REHM are used all warranty claims are void.**



### 11.3 Optional water cooling unit

Part No.: 753 2316

The REHM water cooling unit (see Section 7.4) is adapted to the TIGER DIGITAL with respect to the performance data and the design and allows the use of water-cooled TIG torches. The water cooling unit, together with the TIGER DIGITAL, forms a single unit.

**CAUTION:**

The REHM water cooling unit is only available in combination with the optional cooling unit connection. The cooling unit connection (Part No. 148 0197) must be installed by REHM at the factory.

## 12 Commissioning

### 12.1 Safety information

Carefully read the operating instructions, in particular the Section **2 Safety** information, before commissioning and before beginning work with this welding current source.

#### **Warning!**

**REHM welding equipment should be operated only by persons who are trained and instructed in the use, maintenance and the safety regulations concerning welding systems.**

**When welding always wear protective clothing and take care to avoid other persons who may be in the vicinity being endangered by the UV radiation emitted by the welding arc.**

### 12.2 Working under increased electrical hazard (IEC 874, EN 60974-1, TRBS 2131 and BGR 500 KAP. 2.26)

REHM TIG welding systems meet the regulations for working under increased electrical hazard in accordance with IEC 874, EN 60974-1, TRBS 2131 and BGR 500 KAP. 2.26)

For AC welding a safety unit is built into the electronic control. When AC welding this ensures that the arc is always only ignited with DC voltage and the change to AC current is only made after the welding current is flowing. The machine automatically switches off the HF and the welding current if the arc is suddenly torn away when welding. The machine is then in the basic condition.

It must be noted that for work under increased electrical hazard, the welding current source must not be placed in this area. Regulations EN 60974-1, TRBS 2131 and BGR 500 KAP 2.26 must be observed .



## 12.3 Placement and transportation of the welding unit.

Place the REHM welding system so that the welder has sufficient space in front of unit to adjust and operate the controls. Secure the unit so that it is prevented from tipping over or falling down.

Transport the unit only under compliance with the applicable accident prevention regulations.

### Instructions for placement and transport:

- Transport and operation only in the upright position!
- Transport the unit using only the grips and carrying strap provided.
- Place, operate and transport the unit on a firm, stable and level base
- Safety against tipping is ensured up to an angle of 10° (in compliance with the Standard IEC 60974-1)
- Avoid ambient air containing salt (sea air)!
- Keep entry and exit ports for cooling air free from obstruction!
- Maintain a minimum distance of 0.5m from obstacles!
- The unit is not suitable for crane transport.

**Danger! Electrical voltage!**

**Do not use the welding unit in the open in the rain or snow!**

## 12.4 Connecting the welding unit

Only connect the REHM welding current source to the power supply in accordance with the applicable VDE regulations and also observe the regulations of the respective professional associations.

When connecting the unit observe the instructions concerning the power supply voltage and local mains fuse. Automatic circuit breakers and fuses must always be sized for the stated source current. The necessary information can be found on the rating plate of your unit.

Always switch off the unit when not in use.

Screw the bottle pressure reducer tightly on the thread and check the connection for tightness. Always close the bottle valve after completing work. Observe the regulations of the respective professional associations.

## 12.5 Cooling the welding unit

Place the REHM welding unit so that the air entry and exit ports are not obstructed. The power section can only achieve the specified duty cycle with sufficient ventilation (see "Technical data"). Ensure that no grinding chips, dust or other metallic dust or foreign objects can enter the unit.

## 12.6 Guidelines for working with welding current sources

Only qualified or specially instructed persons who are familiar with the equipment and the process may be assigned with welding work. When welding always wear protective clothing and take care to avoid other persons who may be in the vicinity from being endangered. After finishing the welding work the unit should be left switched on for a few minutes so that the fan continues to run and residual heat is removed from the unit.

## 12.7 Connecting the welding leads and the torch

REHM TIG welding systems are equipped with quick connection devices for connecting the grounding cable and the TIG welding torch as well as the electrode cable. The connection is made by inserting and turning to the right. The protective gas hose is connected to the welding unit via a quick coupling. The torch trigger connector is inserted into the 19 pole socket.



### Important!

To prevent unnecessary energy loss during welding ensure that all welding line connections are tightened and well insulated.

## 12.8 Connection of external components

The connection of external components is achieved via the standard 19 pole remote control socket on the front side of the TIGER DIGITAL. REHM accessories are available for this purpose as described in Section 17.

Only external components listed in this guide may be used. If external components other than those listed are used, the manufacturer's warranty is void.



### Important!

When using the 19 pole remote control socket ensure that the guidelines for the use of serial bus systems are met. Particularly the regulations on electromagnetic compatibility (EMC). Use only the accessories provided by REHM.

To ensure that the initialisation of the external connections is always reliable, first the TIGER DIGITAL power supply switch and then the external devices are switched on.

## 13 Operation

### 13.1 Safety information

Carefully read the operating instructions, in particular the → Section 2, before commissioning and before beginning work with this welding current source.

#### Warning!



**REHM welding equipment should be operated only by persons who are trained and instructed in the use, maintenance and the safety regulations concerning welding systems.**

Working with and maintaining electric welding units is always associated with possible hazards. Persons who are not familiar with this type of system can injure themselves and others. For this reason operating personnel must be made aware of the following potential hazards and the safety measures to prevent possible damage or injury. Irrespective of this, the operator of a welding unit must inform themselves of the safety regulations applicable to the respective operation before starting work.

### 13.2 Electrical hazard



Connecting and maintenance works on the welding unit and their accessories may only be performed in agreement with the applicable VDE regulations and the regulations of the respective professional association.

- Never make contact with live metal parts with the naked skin or wet clothing
- When welding always wear gloves and a welder's hood with an approved protective filter.
- Ensure that everything that you must come into contact with when working, such as your clothing, your work area, the welding torch, the electrode holder and the welding unit are always dry. Never work in wet surroundings.
- Ensure good insulation by only wearing dry gloves and rubber soled shoes and stand on a dry, insulated base, in particular if you stand on metal when working or you are in an area of increased electrical hazard.
- Never use worn or damaged welding cables. Ensure that the welding cables are not overloaded. Only use equipment in a perfect condition.
- Switch off the welding unit during longer periods of interruption.
- Do not wind the welding cables around parts of the housing and do not leave them wound into rings.
- Never leave a powered-up welding unit unattended.

### 13.3 Instructions for your personal safety

The effects of radiation from the electrical arc and the hot metal can result in serious injury to unprotected skin and eyes.

- Only use a welder's hood in perfect condition or automatic welding masks with an approved filter and leather gloves to protect eyes and skin from sparks and radiation from the arc (see TRBS 2131 and BGR 500 SEC. 2.26) Also wear similar protection even if you are only observing the welding work.

- Notify persons in the vicinity of the danger of arc radiation as well as hot metal sputter and parts and protect against these with non-flammable screens.
- Pressurised gas bottles are also a potential hazard. Therefore strictly comply with the safety instructions of the respective professional association and the supplier. Secure protective gas bottles from falling over. Never transport protective gas bottles without a protective cap
- During welding work noise levels of over 70 dBA can occur depending on the process and the environment, this can cause permanent hearing damage. Persons who remain in the working area must, if necessary, wear suitable hearing protection.

### **13.4 Fire protection**

Hot slag or sparks can start a fire if they come into contact with combustible materials, fluids or gasses. Remove all combustible materials from the welding area and make sure that a fire extinguisher is at hand.

### **13.5 Ventilation**

Workplaces must be setup under consideration of the processes, materials and conditions of use so that the air breathed by the user is kept free of substances harmful to health (see TRBS 2131 and BGR 500 KAP. 2.26)

Ensure that the welding area is perfectly ventilated either by natural or artificial ventilation.

Never perform welding work on workpieces treated with paint or degreasing agents that can result in harmful vapours.

## 13.6 Checks before switching on

It is preconditioned that

- the system is properly placed in accordance with → **Section 12 Commissioning**,
- all connections (protective gas, torch connection) are properly made in accordance with → **Section 12, Commissioning**,
- the scheduled periodic maintenance work has been performed in accordance with **Section 15, Maintenance**,
- the safety equipment and the system components (in particular the torch connection hoses) have been checked by the operator, are functional and ready for use,
- the operator and the assisting persons are wearing the appropriate protective clothing and the securing of the work area has been completed so that no uninvolved persons are placed in danger.

## 13.7 Connecting the grounding cable

### Warning!

→ **Section 13.2, Electrical hazard.** Ensure that the welding current cannot flow through lifting device chains, crane cables or other electrical conductors.

→ **Section 13.2, Electrical hazard.** Ensure that grounding cables are connected to the workpiece as close as possible to the welding site. Grounding cables that are connected to distant points reduce the effectiveness and increase the risk of electrical shock and vagrant currents.

## 13.8 Practical instructions for use

The practical instructions for use listed below can only provide an overview of the uses for REHM TIG welding systems. In the event of questions concerning special welding tasks, materials, protective gases or welding fixtures refer to topic-specific publications or specialist recommendations for manufacturers.

With TIG welding a differentiation is made between those materials that can be welded using DC current and those materials that can be welded using AC current. Besides non-alloy, alloy and high-alloy steel DC current can also be used to weld copper, nickel, titanium and their alloys. AC current is generally used to weld aluminium and its alloys.

Various types of tungsten electrodes are offered and used for TIG welding. The difference between them is the share of doping elements in the tungsten electrode. Their compositions are listed in DIN EN ISO 6848 (previously EN 26848) and usually consist of thorium oxide, cerium oxide, zirconium oxide or lanthanum oxide. The advantages of oxide-containing tungsten electrodes are:

- improved ignition properties
- more stable arc
- higher current carrying capacity
- longer lifetime

REHM supply its torches with WC 20 (grey) tungsten electrodes as standard.

The most frequently used electrode diameter and their capacities can be found in the relevant specialist publications. Please consider that the values given are mainly established by machines, which do not have by far the balance range of REHM TIG units. All guidelines state that a specific electrode is exposed to a current that is too high if it drips or takes on a brush-like appearance. You have the choice between lower current or, with AC operation, using a larger minus portion in the balance setting.

When welding with DC the electrode is ground to a point.

With the REHM TIG welding system it is also possible to work in the AC range with balance adjustments in the negative range using a pointed electrode. This offers the advantage that the arc is even more concentrated and effective. In most cases this increases the welding speed.

When grinding the electrode take care that the direction of grinding is in the longitudinal direction of the electrode. For this task use a hazard-reducing grinding apparatus with extraction.

In TIG welding the protective gas is mainly argon. Helium, argon-helium mixture, or argon-hydrogen mixture is used for special applications. Igniting the arc becomes more difficult and the thermal input increases with an increasing portion of helium. The quantity of protective gas required depends on the electrode diameter, size of the gas nozzle, welding current strength and the movement of air depending on the working place. With a workpiece of 4 mm thickness using argon as a protective gas an example reference value for aluminium is approximately 8 litres/minute and for steel and chrome-nickel steel approximately 6 litres/minute. If helium is used the required quantity is significantly higher.

The standard length of the TIG welding torch is 4m and 8m. However, longer torches can be used with these machines. The matching tungsten electrode, clamping sleeve and gas nozzle must be selected depending on the welding task and the current strength. When using a torch with two triggers it is possible to switch the current between the two adjustable values during welding.

Welding additives are added in rod form when welding manually. The correct tungsten must be selected depending on the base material. However, excellent results can be achieved if the weld pool of two parts is allowed to run together, as in the case of corner seams.

With AC welding the negative pole is usually on the electrode. The negative pole is the cooler pole, this means that the current capacity and the service life of the tungsten electrodes is significantly longer than with positive pole welding.

With AC welding the capacity of the electrode is strongly affected by the balance setting. The balance setting is used to distribute the positive and negative share of the welding current between the electrode and the workpiece. During the positive half-wave the aluminium oxide skin is destroyed and a high temperature occurs on the electrode. During the negative half-wave the electrode cools down and the aluminium is heated. As only a short plus pulse is required to break the aluminium oxide skin, the REHM TIG system can be worked with a high negative share.

This has many advantages:

1. The temperature load on the electrode is reduced
2. The electrode can be subject to a stronger current
3. The electrode current range increases
4. Welding can take place with a pointed electrode
5. The arc is narrower
6. The penetration is deeper
7. The thermal influence zone of the weld seam is lower
8. The weld speed is higher
9. The thermal input into the workpiece is reduced

A high-voltage ignition device is installed in the REHM TIGER DIGITAL 2 systems as standard for contactless ignition of the welding arc. The high-voltage causes the path between the tungsten electrode and the workpiece to become so electrically ionised that the welding arc can jump the gap. A higher oxide content in the electrode and a closer distance to the workpiece positively influence the ignition response.

With DC and AC welding the arc can be ignited by the installed program control both with and without high-voltage. Proceed as follows:

The HF setting is positioned at "Off", the tungsten electrode is brought into contact with the workpiece, then the torch trigger is actuated and the electrode is lifted from the workpiece by tipping the torch over the gas nozzle. The ignition of the arc without high-voltage is an advantage if, for example, welding is necessary in a crankcase or repair welding is to be performed on an electronically controlled machine, on which the high-voltage ignition equipment could cause a fault to the control sequence.

REHM TIG systems are particularly suitable as welding current sources for electrode welding due to their fast and precise control dynamics. The current strength setting and polarity depends on the electrode manufacture. Positive pole welding is used when welding with basic electrodes.

More information can be found in the book series from

DVS-Verlag GmbH  
Aachener Str. 172  
40223 Düsseldorf  
[www.dvs-verlag.de](http://www.dvs-verlag.de)

## 14 Faults TIG welding unit

### 14.1 Safety information

#### **Warning!**

If a fault occurs that represents a hazard to persons, systems and/or the environment, switch off the system immediately and secure against restarting.

Only restart operations with the system after the fault has been eliminated and no hazard exists for persons, machines and/or the environment.

Faults must only be eliminated by qualified persons under the observance of all safety instructions. → Section 2

Before restarting the system must be released by qualified personnel.

### 14.2 Table of faults

#### **REHM control panel is not working**

**The digital display instrument has no display and no LEDs illuminate.**

Cause:

Mains power supply is missing  
(possible mains fuse)  
Mains cable of plug is defective

Remedy:

Check the mains voltage  
  
Check

#### **Current slope-up time & current slope-down time are at "0.0" and cannot be altered.**

Cause:

Remote foot control is plugged in  
controller.

Remedy:

Times are controlled by the remote  
Unplug the remote controller.

#### **Current slope-up time & current slope-down times are not complied with**

Cause:

Starting current is set at 100%  
End crater current is set at 100%

Remedy:

Reduce starting current  
Reduce the end crater current  
value

#### **4 cycle cannot be set**

Cause:

Remote foot control is plugged in

Remedy:

Unplug the remote foot control

#### **Balance and frequency cannot be selected**

Cause:

Polarity is not "~"

Remedy:

Only adjustable in the AC range



**When switched on the system has different parameters than those when it was switched off**

Cause:

Values are only saved after a successful welding process.

Remedy:

Execute welding process

**No protective gas flows**

Cause:

Bottle is empty or the gas hose is kinked.  
Pressure reduced is defective.  
Gas value on the machine is defective.  
Blade terminal on the gas valve is loose.  
Welding process "Electrode"

Remedy:

Check  
Check  
Service call  
Check  
Gas valve remains closed

**Rotation of the fan is not audible**

Cause:

Fan speed level is dependent on demand when at low temperature the fan runs at loads.  
lower speed or switches off.

Remedy:

Check whether the fan is running at higher speed under higher

Fan defective.

Service call

**No high voltage pulse**

Cause:

HF ignition is set to off  
No protective gas present  
Grounding cable poorly connected  
Electrode dirty  
Electrode not suitable  
Gas pre-flow time too long until time expires.  
High-voltage flashover in the torch  
Connection between the torch and the grounding cable reversed

Remedy:

Switch on the HF ignition  
Check  
Check  
Grind  
Change electrode  
Reduce gas pre-flow time or wait  
  
Change the torch  
Connect correctly

**Welding current does not reach the set value or the arc does not burn.**

Cause:

Grounding cable poorly connected  
Foot controller connected and not actuated.  
Hand remote control connected control  
No or incorrect protective gas

Remedy:

Check  
Check  
  
Set the current on the remote  
  
Check

**Arc sputters and jumps**

Cause:

Electrode and workpiece do not reach working temperature  
Electrode is poorly sharpened  
Electrode not suitable

Remedy:

Use thinner electrodes  
  
Grind electrode  
Change electrode

**Arc has a strange colour**Cause:

No or too little protective gas

Electrode dirty

Remedy:

Check

Grind

**Electrode burns off**Cause:

No protective gas

Current load too high

Pulse share too high with AC current welding

Connection between the torch and the grounding cable reversed

Electrode welding is set

Remedy:

Check

Use a thicker electrode

Increase the negative share using balance

Connect correctly

Set TIG welding

**System does not pulse**Cause:

Pulse is not switched on

Values for T1 and T2 are equal

Remedy:

Set pulse time T1 and / or T2

Change the values

**Arc breaks away on ignition**Cause:

Ignition energy set too low

Electrode is consumed or dirty

Remedy:

Set the ignition energy or use thinner electrode

Grind electrode

### 14.3 Error messages

Error	Acknowledge			Error	Cause	Elimination
	A	B	C			
2	✓	-	-	Mains voltage	Mains voltage outside the tolerance range	Switch the unit off and check the mains voltage
18	-	✓	-	Condensation moisture	Condensation / moisture on the inside of the unit	Wait until the condensation / moisture has disappeared from the inside of the unit.
19	-	-	✓	Remote foot controller	The foot controller is removed during welding.	Do not remove the foot controller during welding.
21	-	✓	-	TIG torch in EL mode	EL mode active with a TIG torch connected	Remove the TIG torch Switch to TIG mode
22	-	-	✓	Secondary short circuit	When switching from TIG to electrode a short circuit is present on the welding socket.	Eliminate the short circuit on the welding socket Eliminate the fault.
23	✓	-	-	Primary short circuit	A short circuit is present on the welding socket when switching on. Internal short circuit	Eliminate the short circuit on the welding socket.  Service call
33	-	-	✓	Reversing pole current or reversing pole power is too high	Welding circuit inductance too high	Change the torch and grounding cable run. No loops and windings.
34	-	✓	-	Remote control connected to the torch socket	Connected torch is not detected.	Use a Rehm torch Defective torch.
35	-	✓	-	Coolant overtemperature	Temperature of the coolant > 65°C	Let the water cooler cool down Top-up coolant
48*	-	-	✓	Coolant flow	Coolant monitor detects low coolant flow Coolant monitor blocked by dirt	Immediately switch off the current source Check that the connecting cable is plugged in Check the coolant level Check the connections on the water cooled torch Eliminate interruptions in the coolant circuit Bleed the coolant circuit Check the pump
> 51				Service call	An analysis of the cause can be made by the service technician	

\* Only for TIGER DIGITAL with an integrated water cooling unit

Acknowledge legend

- A Fault message can be reset by switching off and back on again.
- B Fault message will go out automatically when the fault is eliminated
- C Fault message will go out when the fault is eliminated and the push and rotatory encoder **[Fig.8]** is actuated. If the fault is still present the fault message will reappear in the display screen **[Fig.5]** after 2 seconds.

## 15 Maintenance work

### 15.1 Safety information

#### Warning!

Maintenance and repair work may only be performed by persons who have been trained by REHM. Please contact your REHM dealer. When replacing parts only use REHM original spare parts.

If maintenance or repair work is performed on this unit by persons who have not been trained and authorised to carry out the work by REHM, then claims against REHM become void.

Before beginning cleaning work the unit must be switched off and disconnected from the mains supply.

Before maintenance work the welding system must be switched off and disconnected from the mains supply and secured against unintended reconnection.

Supply lines must be shut off and vented free of pressure.

The warning notices listed in →Section 2 “Safety” must be observed.

The welding system and its components must be maintained in accordance with the requirements of the operating and maintenance instructions.

Insufficient or improper maintenance or repair may result in operating faults. Periodic maintenance of the system is therefore essential. No constructive change or additions may be made to the system.

### 15.2 Maintenance table

The maintenance intervals are recommended by REHM for standard requirements (for example, single shift operation, use in a clean and dry environment). The precise maintenance intervals are specified by your safety officer.

Activity	Interval
Cleaning the inside of the unit	depending on the conditions of use
Functional test of the safety equipment by operating personnel	Daily
Visual system check, particularly the torch hoses	Daily

Activity	Interval
Check the function of the residual current circuit breaker	Daily (in flying constructions) otherwise monthly
Have the connecting lines and torch hoses checked by qualified personnel; log the checks in the logbook provided. <b>Perform checks more regularly depending on the country-specific laws.</b>	Every six months
Have the complete welding system checked by qualified personnel; log the checks in the logbook provided. <b>Perform checks more regularly depending on the country-specific laws.</b>	Annually

### 15.3 Cleaning the inside of the unit

If the REHM welding unit is used in a dusty environment the inside of the unit must be cleaned at regular intervals by blowing out or vacuuming.

The frequency of this cleaning depends on the respective conditions of use. Only use clean, dry air to blow out the unit or use a vacuum cleaner.

If maintenance or repair work is performed on this unit by persons who have not been trained and authorised to carry out the work by REHM, then and claims against REHM become void.

### 15.4 Proper disposal



Only for EU countries

Do not dispose of electric appliances in domestic waste!

In accordance with the European Directive 2002/96/EC concerning old electrical and electronic devices and its transposition into national law, used electrical appliances must be collected separately and recycled in an environmentally friendly manner.

## 16 Technical data

	180 DC	230 DC	180 AC/DC	230 AC/DC
Mains voltage $U_1$ * <sup>1</sup>	1 x 230 V	1 x 230 V	1 x 230 V	1 x 230 V
Mains voltage tolerance				
without water cooling	-15% / +10%	90V... 265 V	-15% / +10%	90V .. 265 V
with water cooling	-15% / +10%	-15% / +10%	-15% / +10%	-15% / +10%
Mains frequency	50 Hz / 60 Hz	50 Hz / 60 Hz	50 Hz / 60 Hz	50 Hz / 60 Hz
Mains fuse	16 A slow-blow	16 A slow-blow	16 A slow-blow	16 A slow-blow
Effective primary current $I_{1\text{Eff}}$	24.9 A	18.7 A	24.9 A	18.7 A
Max. primary current $I_{1\text{max}}$	26.8 A	25.3 A	26.8 A	25.3 A
Max. power at $I_{1\text{max}}$	6.1 kVA	5.8 kVA	6.1 kVA	5.8 kVA
cos $\varphi$	0.98	0.99	0.98	0.99
Recommended residual current circuit breaker	Type B	Type B	Type B	Type B
Open-circuit voltage $U_2$ * <sup>2</sup>	90 V	90 V	95 V	95 V
Setting range $I_2$				
TIG	4 A – 180 A	4 A – 230 A	4 A – 180 A	4 A – 230 A
Electrode	20 A – 140 A	20 A – 150 A	20 A – 140 A	20 A – 150 A
Electrode booster	20 A – 150 A	20 A – 180 A	20 A – 150 A	20 A – 180 A
Duty cycle (ED) at 40°C				
35% ED		225 A		225 A
40% ED	180 A		180 A	
60% ED	160 A	180 A	160 A	180 A
100% ED	140 A	160 A	140 A	160 A
30% ED	150 A		150A	
40% ED		180 A		180 A
60% ED	140 A	160 A	140 A	160 A
100% ED	130 A	140A	130 A	140 A
Standard operating voltage				
TIG	10.2 V – 17.4 V	10.2 V – 19.0 V	10.2 V – 17.4 V	10.2 V – 19.0 V
Electrode	20.8 V – 26.6 V	20.8 V – 27.2 V	20.8 V – 26.6 V	20.8 V – 27.2 V
Peak voltage HF $U_p$	9.7 kV	9.7 kV	9.7 kV	9.7 kV
Generator power for $I_{2\text{max}}$	8.2kVA	8.2kVA	8.2kVA	8.2kVA
Generator type	Synchronous, asynchronous	Synchronous, asynchronous, inverter	Synchronous, asynchronous	Synchronous, asynchronous, inverter
Protection type * <sup>3</sup>	IP 23 S	IP 23 S	IP 23 S	IP 23 S





	180 DC	230 DC	180 AC/DC	230 AC/DC
Protection class				
without water cooling * <sup>4</sup>	2	2	2	2
with water cooling	1	1	1	1
Insulation class * <sup>5</sup>	F	F	F	F
EMV emissions class	A	A	A	A
Cooling type	AF	AF	AF	AF
Overvoltage category	III	III	III	III
Torch cooling				
without water cooling	Gas	Gas	Gas	Gas
with water cooling	Water	Water	Water	Water
Noise emission * <sup>6</sup>	< 70dB(A)	< 70dB(A)	< 70dB(A)	< 70dB(A)
Maximum protective gas pressure	6 Bar (87.02 psi)	6 Bar (87.02 psi)	6 Bar (87.02 psi)	6 Bar (87.02 psi)
Dimensions L x B x H				
without water cooling	480x160x320 mm	480x160x320 mm	480x160x320 mm	480x160x320 mm
with water cooling	480x215x530 mm	480x215x530 mm	480x215x530 mm	480x215x530 mm
Weight (without coolant)				
without water cooling	7.1 kg	7.5 kg	7.3 kg	7.9 kg
with water cooling	15.6 kg	16.0 kg	15.8 kg	16.4 kg
Standards	60974-1 60974-2 60974-9 60974-10 CE	60974-1 60974-2 60974-9 60974-10 CE	60974-1 60974-2 60974-9 60974-10 CE	60974-1 60974-2 60974-9 60974-10 CE

<b>Water cooling*</b>	
Cooling power	
at 1 l/min (25°C)	600 W
at 1 l/min (40°C)	330 W
Max (25°C)	1000 W
Max (40°C)	500 W
Maximum flow rate	2.5 l/min
Maximum pump pressure	4.0 Bar 58.0 psi
EMC protection class	A
Tank content	1.5 l
Pump	Centrifugal pump
Monitoring flow	Error message below 0.5 l/min
Monitoring coolant	Error message above 65°C
Fuse	10 A slow-blow

\* for a separately available water cooling unit

1	Mains voltage	The unit may only be operated and connected with a grounded mains (grounded neutral and protective conductor).
2	Open-circuit voltage U <sub>2</sub>	Measured open-circuit voltages, which are below the permissible tolerance according to EN60974-4 for voltages, less than the open-circuit voltage specified on the type plate, pose no danger and do not change the welding properties.
3	Protection type	<p>Protection type IP23 S</p> <ul style="list-style-type: none"><li>- Protection of the unit against ingress of solid foreign bodies Ø larger than 12 mm</li><li>- Protection of the unit against spray water up to an angle of 60° from the vertical.</li></ul> <p>The unit should be placed and operated outdoors in accordance with the protection class. The device must not to be operated, transported and stored in rain or snow.</p>
4	Protection class	<p>Protection class 2:</p> <p>The PE connection serves as EMC discharge and must be connected.</p> <p>The continuity test for the PE should be omitted for tests according to protection class 1, as the PE connection is not placed on housing components in the case of a device of protection class 2.</p>
5	Insulation class	Class of insulation materials used and their maximum permissible continuous temperature (F = maximum permissible continuous temperature 155°)
6	Noise emission	Idle and operating with a standard load according to IEC 60974-1, at the maximum working point.

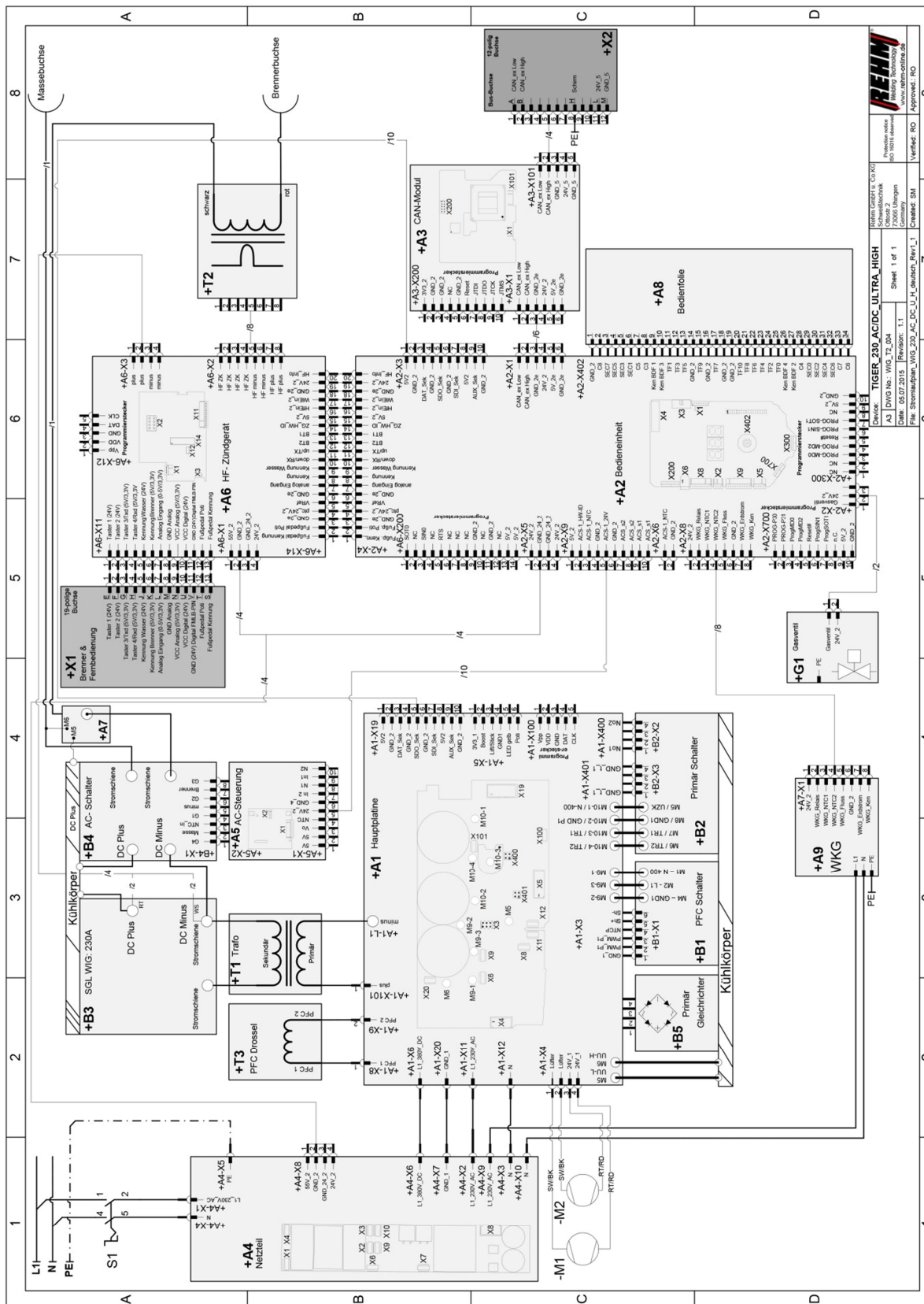
Subject to technical changes through further development.

## 17 Accessories

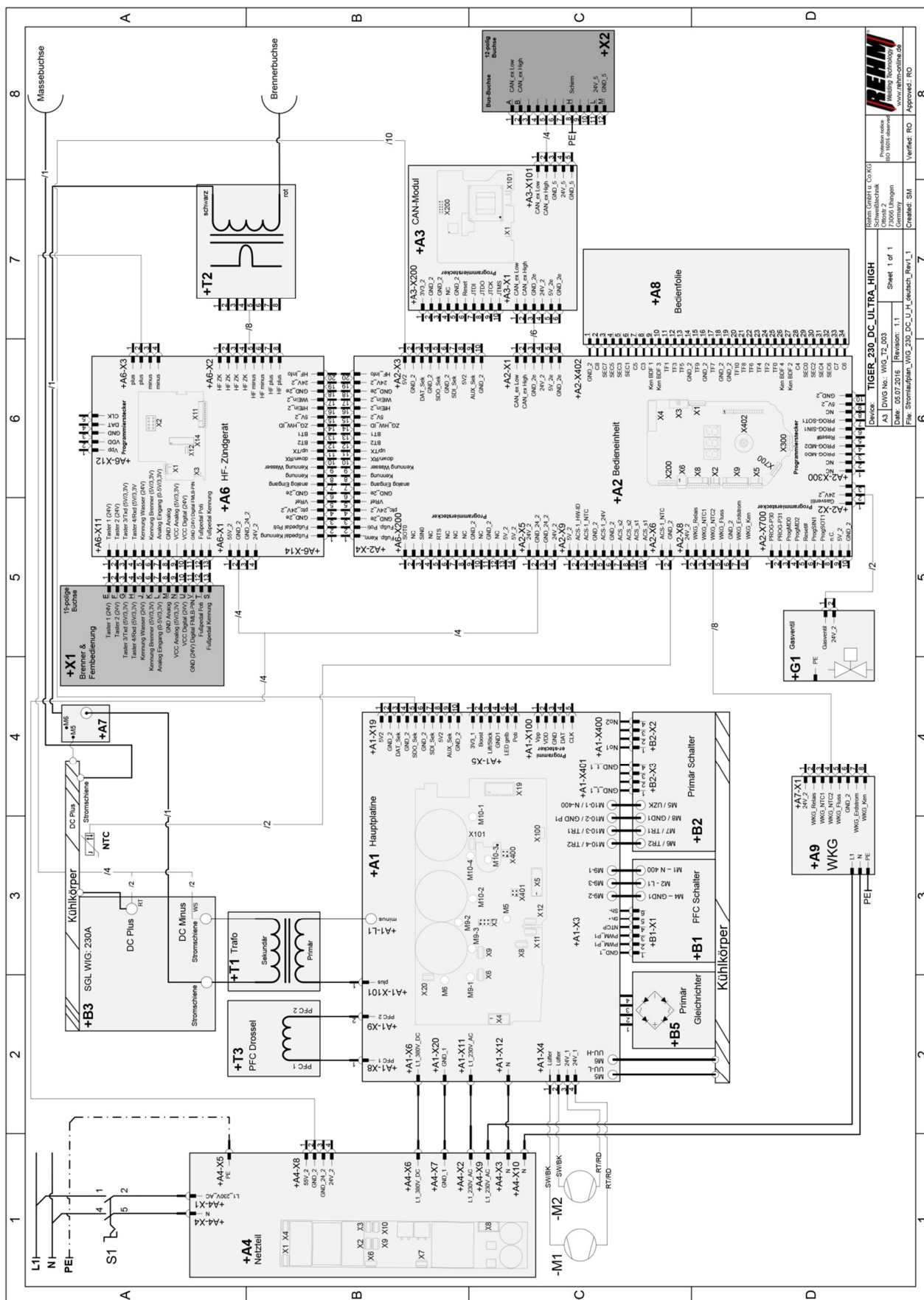
REHM-part number	Name
<b>Ground cable</b>	
7810101	Ground cable 25 mm <sup>2</sup> 4 m 13 mm 400A clamp
<b>Electrode cable</b>	
7810201	Electrode cable 25 mm <sup>2</sup> 5m 13mm with 260A mount
<b>Pressure reducer</b>	
7830100	Pressure reducer with content and work pressure gauge, 200 bar, 32l/min
7830150	Pressure reducer with content and work pressure gauge, 200 bar, 32l/min, Netherlands version
<b>Gas hose</b>	
2200641	Gas hose 1.4m
7501111	Protective gas filter 1/4" mounting between the gas hose and pressure reducer
<b>Welding torch</b>	
<b>TIG torch with 19 pin connector for TIGER DIGITAL 180/230, Gas cooled to max. 150A DC</b>	
7633300	R TIG 140 19 4m UD HighFlex leather
7633301	R TIG 140 19 8m UD HighFlex leather
7631848	R SR 17 19 4m UD HighFlex leather
7631849	R SR 17 19 8m UD HighFlex leather
7631802	R TIG 150 19 4m UD GRIP-LITTLE HighFlex leather
7631803	R TIG 150 19 8m UD GRIP-LITTLE HighFlex leather
<b>TIG torch with 19 pin connector for TIGER DIGITAL 180/230, Gas cooled to max. 240A DC</b>	
7633400	R TIG 210 19 4m UD HighFlex leather
7633401	R TIG 210 19 8m UD HighFlex leather
7633133	AE 210 19 4m UD HighFlex leather
7633134	AE 210 19 8m UD HighFlex leather
7631850	R SR 26 19 4m UD HighFlex leather
7631851	R SR 26 19 8m UD HighFlex leather
631804	R TIG 200 19 4m UD GRIP HighFlex leather
631805	R TIG 200 19 8m UD GRIP HighFlex leather
<b>Water cooling</b>	
7633500	R TIG 250W 19 4m UD HighFlex leather
7633501	R TIG 250W 19 8m UD HighFlex leather
7633135	AQ 310W 19 4m UD HighFlex leather
7633136	AQ 310W 19 8m UD HighFlex leather
7631852	R SR 20W 19 4m UD HighFlex leather
7631853	R SR 20W 19 8m UD HighFlex leather
7631806	R TIG 260W 19 4m UD GRIP-LITTLE HighFlex leather
7631807	R TIG 260W 19 8m UD GRIP-LITTLE HighFlex leather
7631808	R TIG 260SC 19 4m UD GRIP HighFlex leather
7631809	R TIG 260SC 19 4m UD GRIP HighFlex leather

REHM-part number	Name
<b>Torch wear parts sets</b>	
7700435	Wear parts set R SR 17/26
7700440	Wear parts set R SR 20
7700426	Wear parts set R TIG 200
7700425	Wear parts set R TIG 150/260W
<b>Remote control</b>	
7531051	Foot-actuated remote controller TIGER DIGITAL 180/230
<b>Fitting cases</b>	
2600366	Fitting case for set (plastic, unequipped)
2600355	Aluminium transport box 850x350x350mm (LxWxH)
<b>Coolant</b>	
1680075	Coolant RCL 5 litre
1680077	Coolant RCL 25 litre
<b>Adapter for accessories</b>	
3600615	Torch duo cable 19-pin
3600650	Torch adapter cable INVERTIG.PRO to TIGER DIGITAL 180/230
3600628	Torch adapter cable TIGER DIGITAL 170/210 to TIGER DIGITAL 180/230 water cooled
3600629	Torch adapter cable TIGER DIGITAL 170/210 to TIGER DIGITAL 180/230 gas cooled
<b>Optional water cooling unit (only together with the optional water cooling unit connection)</b>	
7532316	Water cooling unit TIGER DIGITAL
1480197	Optional cooling unit connection (factory installed)

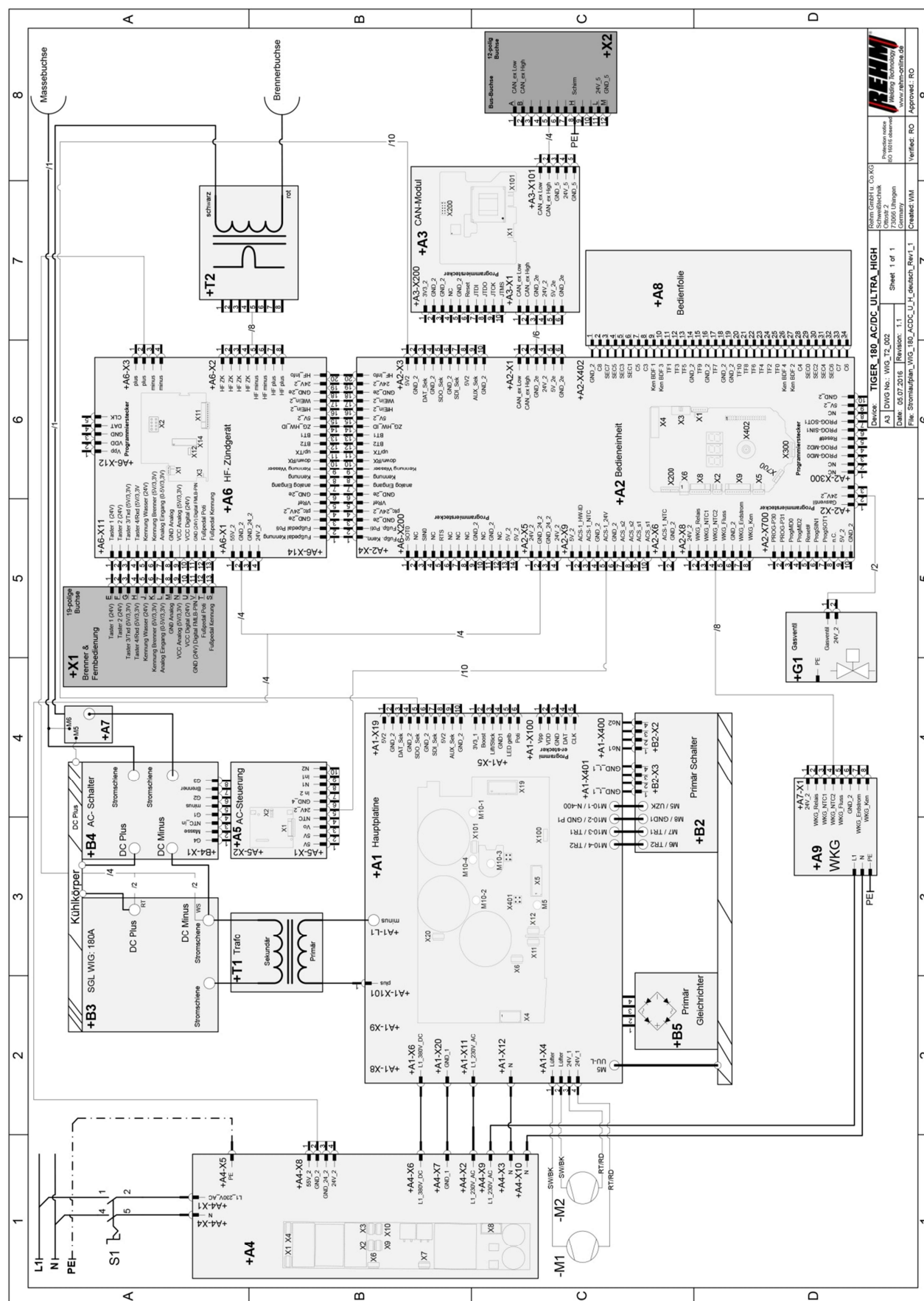
### Circuit diagram TIGER DIGITAL 230 AC/DC



Circuit diagram TIGER DIGITAL 230 DC

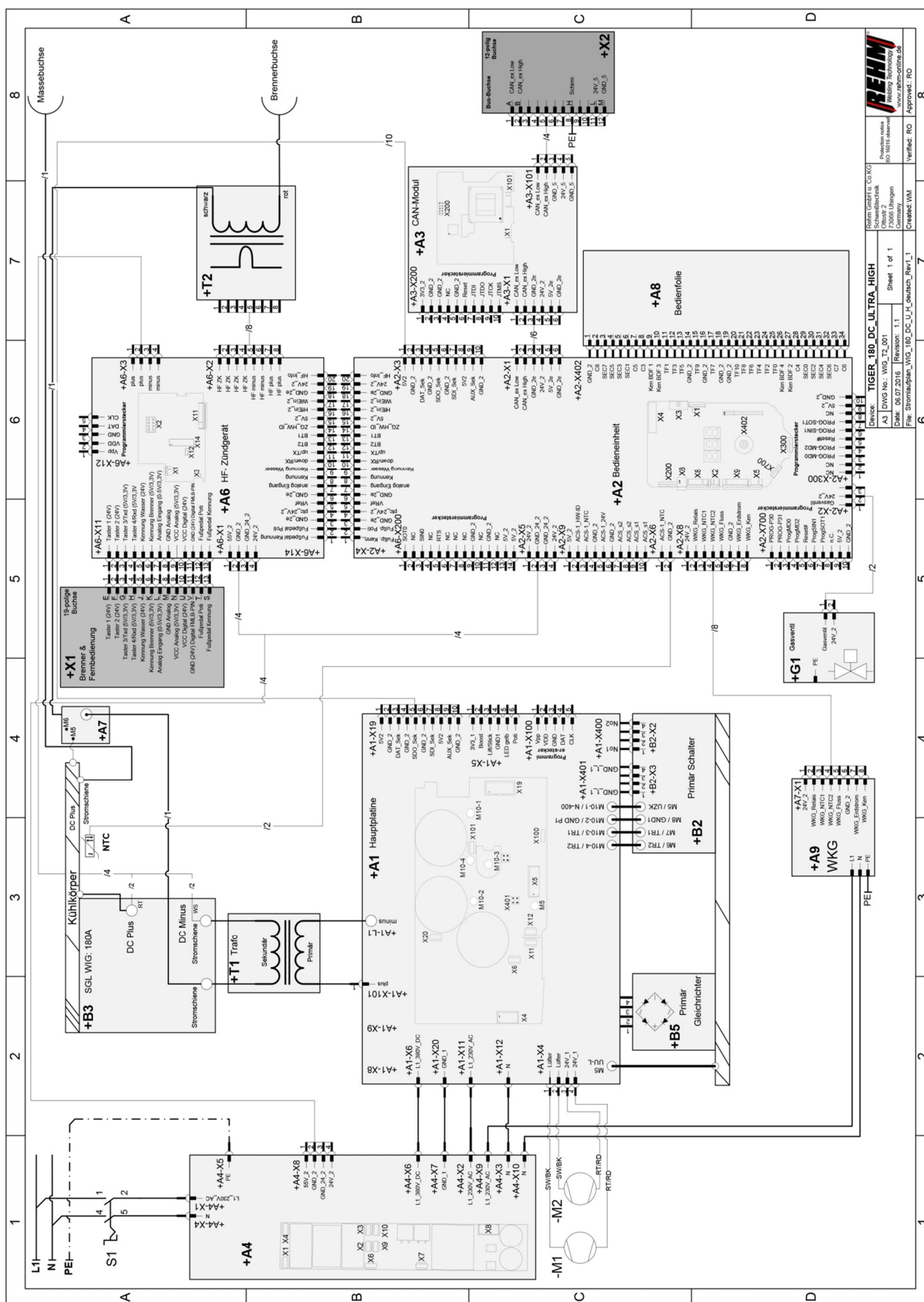


### Circuit diagram TIGER DIGITAL 180 AC/DC





Circuit diagram TIGER DIGITAL 180 DC

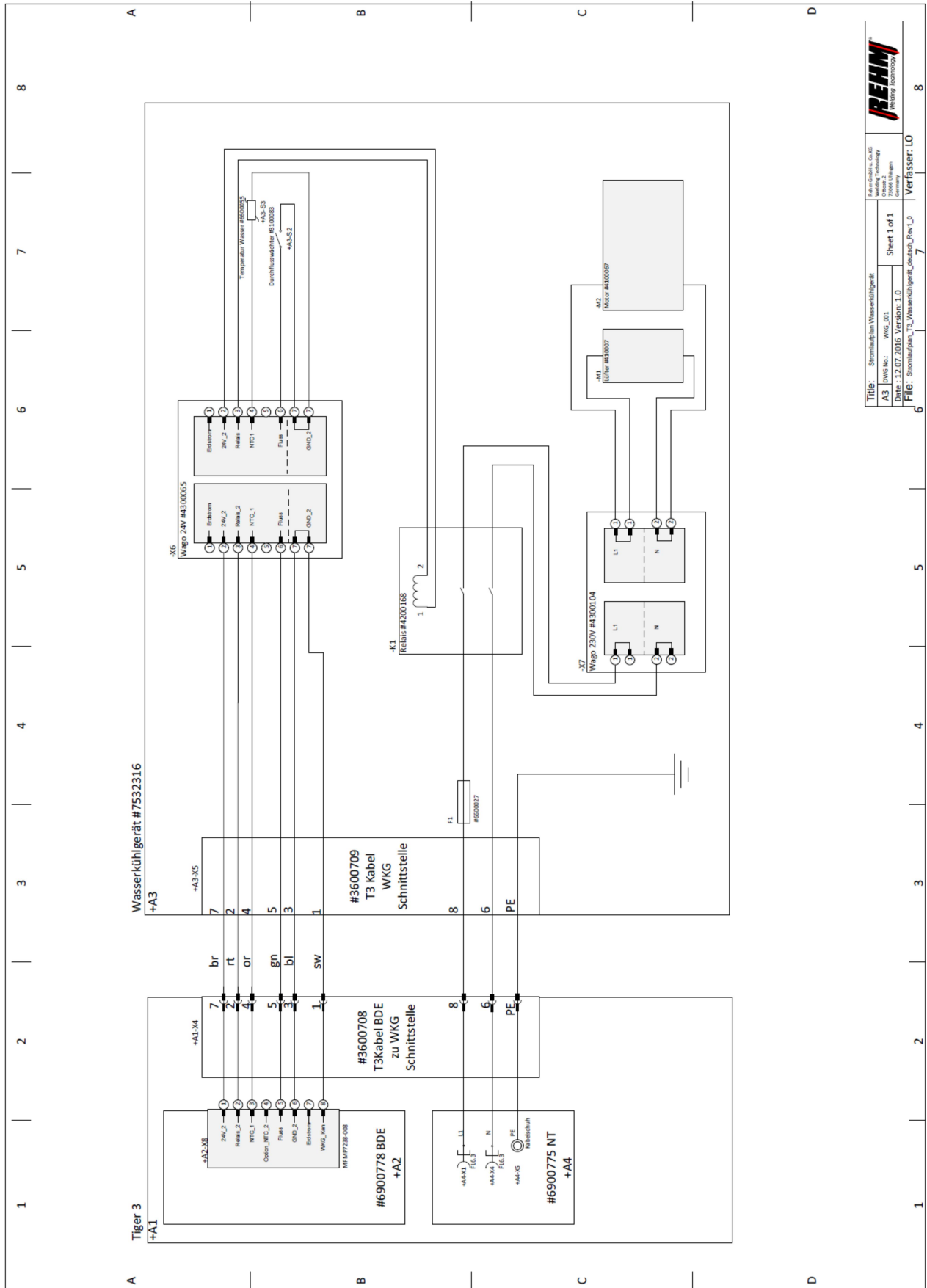




## Legend to the circuit diagram

Identifier	Name
A1	Main board
A2	Operating unit
A3	CAN-module
A4	Power supply
A5	AC control
A6	HF ignition device
A7	HF interference suppression
A8	Operation film
A9	Water cooling device
B1	PFC switch
B2	Primary switch
B3	Secondary rectifier
B4	AC switch
B5	Primary rectifier
G1	Gas valve
M1	Fan
M2	Fan
S1	Main switch
T1	Power transformer
T2	Ignition transformer
T3	PFC choke
X1	Torch & remote control socket
X2	iSystem socket

Circuit diagram TIGER DIGITAL water cooling unit



Title: Stromlaufplan Wasserkuhlergerät	
A3	WKS 001
Date: 12.07.2016 Version: 1.0	
File: Stromlaufplan_T3_Wasserkuhlergerät_Revis_1.0	
Verfasser: LO	

## 19 INDEX

### "

"Automatic .....	36
"Cleaning .....	67
"Commissioning" .....	52
"Connecting .....	53, 57
"DVS" .....	59
"Faults" .....	60
"Health .....	11
"High .....	26
"Increased .....	52
"Index" .....	80
"Instructions .....	57
"Intended .....	9
"Lift-Arc" .....	27
"List .....	3
"Occupational .....	11
"Other .....	8
"Placement .....	53
"Qualification of 12 .....	11
"Residual .....	11
"Safety .....	6, 10, 11
"Storing .....	12
"Symbol" .....	9
"Warning .....	10

### A

AC welding .....	59
Accessories .....	72
<b>Applications</b> .....	11

### C

Changes .....	12
Circuit diagrams .....	74

### D

DC welding .....	59
------------------	----

### F

Function description .....	15
----------------------------	----

### G

Gap bridging" .....	28, 33
---------------------	--------

### I

Ignition .....	59
Inert gases .....	58

### M

Maintenance intervals" .....	66
Maintenance work" .....	55, 66
Manufacturer .....	2

**O**

Operating mode .....	23
Operation	
checks before switching on" .....	57
Out of position welding" .....	28, 33

**P**

Product identification	
Machine name .....	2
Type number .....	2
Protective gas consumption" .....	35
Pulsing" .....	33
Purpose of the document .....	12

**R**

Rod electrodes .....	59
----------------------	----

**S**

Safety	
Hazards of non-compliance .....	11

**T**

Technical data .....	68
TIG welding torch .....	58
Tungsten electrodes .....	57
Typographic distinctions .....	9



**EC declaration of conformity**

For the following named products

**TIG - protective gas - welding machine**

<b>TIGER DIGITAL 230 DC ULTRA</b>	<b>TIGER DIGITAL 180 DC ULTRA</b>
<b>TIGER DIGITAL 230 AC/DC ULTRA</b>	<b>TIGER DIGITAL 180 AC/DC ULTRA</b>
<b>TIGER DIGITAL 230 AC/DC HIGH</b>	<b>TIGER DIGITAL 180 AC/DC HIGH</b>
<b>TIGER DIGITAL 230 DC HIGH</b>	<b>TIGER DIGITAL 180 DC HIGH</b>
<b>TIG.STAR 170 DC AC/DC</b>	

it is hereby confirmed that they comply with the essential protection requirements which are laid down in the Directive **2004/108/EU** (EMC Directive) of the council on the approximation of the laws of the Member States relating to electromagnetic compatibility and in the Directive **2006/95/EU** relating to electrical equipment designed for use within certain voltage limits.

The above products comply with the requirements of this directive and comply with the safety requirements for arc welding devices in accordance with the following product standards:

**EN 60 974-1: 2013-06**

Arc welding equipment - Part 1: Welding power source

**EN 60 974-2: 2013-11**

Arc welding equipment - Part 2: Liquid cooling systems

**EN 60 974-3: 2014-09**

Arc welding equipment - Part 3: Arc striking and stabilizing devices

**EN 60974-10: 2008-09**

Arc welding equipment - Part 10: Electromagnetic compatibility (EMC) requirements

according to the EC. Directive 2006/42/EC article 1, paragraph 2 the above mentioned products fall exclusively within the scope of the directive 2006/95/EC relating to electrical equipment designed for use within certain voltage limits.

This declaration is given for the manufacturer:

REHM GmbH u. Co. KG Schweißtechnik  
Ottostr. 2  
73066 Uhingen

UHINGEN, 16/08/2017

submitted by

R. Stumpp

*Managing Director*

# REHM – The benchmark for modern welding and cutting

## THE REHM product range

### ■ REHM TIG/MAG inert gas-welding equipment

SYNERGIC.PRO<sup>2</sup> gas and water cooled up to 450 A

SYNERGIC.PRO<sup>2</sup> water cooled 500 A up to 600 A

MEGA.ARC continuously adjustable up to 450 A

RP REHM Professional up to 560 A

PANTHER 202 PULS pulse welding equipment with 200 A

SYNERGIC.PULS pulse welding equipment up to 400 A

MEGA.PULS FOCUS pulse welding equipment up to 500 A

### ■ REHM TIG inert gas-welding equipment

TIGER, mobile 100 KHz inverter

INVERTIG.PRO TIG welding equipment

INVERTIG.PRO *digital* TIG welding equipment

### ■ REHM inverter technology

TIGER and BOOSTER.PRO 100 KHz electrode inverter

### ■ REHM Plasma cutting systems

#### ■ Welding accessories and consumables

#### ■ Welding gas extraction

#### ■ Welding turntable

#### ■ Technical welding advice

#### ■ Torch repairs

#### ■ Service

Development, design and production – all under one roof – at our plant in Uhingen. Thanks to this central organisation and our forward-looking commitment, new insights can be quickly incorporated into the production process. The requests and requirements of our customers form the basis of an advanced product development. A variety of patents and awards represent the precision and quality of our products. We place customer proximity and competence at the forefront of our consulting, training and service activities.

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